

BEST COPY
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THEORIA
MOTUS LUNAE
EXHIBENS
OMNES EIVS INAEQUALITATES

IN

ADDITAMENTO.

HOC IDEM ARGUMENTUM ALITER TRACTATUR
SIMULQUE OSTENDITUR
QUEMADMODUM MOTUS LUNAE CUM OMNIBUS
INAEQUALITATIBUS

INNUMERIS ALIIS MODIS

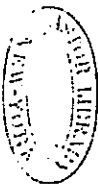
REPRESENTARI
ATQUE AD CALCULUM REVOCARI POSSIT

AUCTORE

L. EULER O



IMPENSIS
ACADEMIAE IMPERIALIS SCIENTIARUM
PETROPOLITANAE
ANNO 1723.





Academiam Scientiarum Petropoltanam triennio abhinc omnes, qui ingenii viribus confisi, ad examinandam Newtonianam de motu Lunae Theoriam, animum applicare vellent, invitasse, atque ei, qui in hac parte tenuisset primas, prae-mii loco proposuisse nummos aureos centum; postmodum Celeberrimum Clairautum huius certaminis existisse victricem, publico Academicorum, qui Petropoli agunt, iudicio divulgatum.

* 2

Cele-



Celeberrimus Eulerus, Academiae Petropolitanae membrum honorarium, officii sui esse existimavit, ferre vna cum ceteris illa Clairauti dissertatione iudicium. Transmisit ergo huc ad nos vna cum sua sententia amplissimam de eodem argumento dissertationem; quae quo celerius innotesceret, visum est Academiae Praefidi, minoris Russiae Hetmano Illustrissimo Cyrillo Gregoridæ, Comiti Rasumovio, eam tradere Academicis in solenni conventu examinandam, ea fini, vt si suffragio Academicorum comprobata, dignaque iudicata foret, quae orbis eruditi proponeretur theatro, ea praelo quam maturissime subiceretur; quandoquidem ille mos iam inde a principio obtinuit, vt, quae in publico coetu praeleguntur dissertationes, eae vel ante solemnem actum, vel parvulo intermisso spatio typis diuulgentur postea.

Cetera.



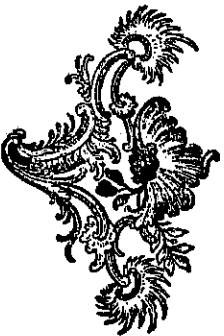
Ceterum dissertatio illa constat magnam partem calculis, veris quidem illis et omnibus numeris absolutis, sed propter nimiam sui molem atque difficultatem auditu molestissimis: quae si recitarentur publice, periculum erat, ne auditorum animi auctantandis iis deficerent, neue Academia Summorum patientia. Virorum abivi, caeterosque enicare odio videretur. Praevidit hoc incommodum, providitque Illustrissimi Praefidis sapientia. Mandavit Astronomiae Professori V. C. Nicetae Popovio, cuius id temporis dicendi erat provincia, vt proximam illam Euleri dissertationem, omiffis calculis, redigeret incompendium, et quae inde exceperet, auditorum causa recitaret publice. Quo quidem facto et auribus hominum consultis, et tamen rerum capitum participes eos facere aequabili temperamento instituit: at-

VI



que dissertationem, ne quid forte naeuorum obreperet, ipso auctore coram typis excudi aequum censuit.

Iam qui illo tempore interfuerant conuentui Academicorum solenni auditores, aequis nimis auribusque auscultarunt excerpta recitantem Euleriana Propositionum: est ergo quod sperare liceat, et iis, quorum interest, vt qui hoc genere studiorum maxime delectantur, factum irifatis ipsa dissertatione. Datum Petropoli Nov. 1752.



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INTRO.

❶ (○) ❷

INTRODUCTIO.

Quam nullam sit dubium, quin summi Newtoni Theo-
 ria, qua motum Planetarum felicissimo cum suc-
 cessu certis legibus adstrinxit, plurimum ad mo-
 tum Lunae accuratius determinandum contulerit, maximi
 sane in Astronomia momenti est quaestio: utrum haec
 Newtoni Theoria omnino sit sufficiens omnibus motus in-
 aequalitatibus, quae in Luna observantur, exactissime ex-
 plicandis nec ne? Quanquam autem a Newtoni affectis
 plerumque affirmari solet, nullam in motu Lunae observari
 inaequalitatem, cuius ratio in ista Theoria non condineatur;
 tamen tantum abest, ut hic consensus a quoquam perspi-
 cue sit monstratus, ut potius applicatio huius Theoriae ad
 Lunam tantum simpliciter calculi difficultatibus, quibus pe-
 nitus evolvendis vires ingenii humani vix sufficere viden-
 tur. Plurimae quidem adhuc prodierunt Tabulae Lunares,
 quae ex Theoria Newtoniana deductae perhibentur, sed
 praeterquam quod saepius ultra 5' ab observationibus di-
 scerent, earum convenientia cum Theoria ipsa nequaquam
 est euisa; quin potius pleraeque Tabulae inaequalitatum
 non tam Theoriae quam observationibus sunt superstructae.
 Huiusmodi ergo tabularum sine consensus sine dissentis
 cum observationibus neque ad Theoriam Newtonianam
 plenissime confirmandam, neque ad eam infringendam alle-
 gari

INTRO.

A

gari potest: nam quatenus istae tabulae observationibus satisfaciunt, hoc non soli Theoriae est tribuendum; quatenus autem cum observationibus minus conveniunt, hoc ne Theoriae quidem imputari poterit, propterea quod istae Tabulae non soli Theoriae imputantur.

Quaestio itaque, cujus mentionem feci, recte enodari nequit, nisi ante eiusmodi Tabulae exhibeantur, quae ex sola Theoria, nullis observationibus in subsidium vocatis, sint formatae; tum enim demum ex huiusmodi Tabularum collatione cum ingenti observationum summo studio institutarum copia diiudicare licebit, utrum Theoria omnibus observationibus respondeat, an vero correctione quampiam indigeat. Non difficile quidem est ex principis mechanicis motum Lunae aequationibus analyticis complecti; quoniam autem hae aequationes plures variabiles inter se permixtas continent, atque adeo differentialibus secundi ordinis implicentur, earum resolutio maximis difficultatibus est obnoxia; et quoniam alio modo nisi per approximationem suscipi non potest, utcumque inditatur, semper non levis dubium remanet, utrum partes, quae in calculo sunt neglectae et praetermissae, nihil, quod in motu Lunae esset notabile, efficere possent. Hoc modo explicatio motuum Lunae tota ad solam Analyſin transferretur, ac difficultates, quibus premitur, inde oriuntur, quod Analyſis nondum facta est exsulta.

Cum igitur Theoria Newtoniana hoc principio latissime patente imitatur, quod omnia corpora coelestia se mutuo attrahant in ratione reciproca duplicata distantiarum,

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rum, si motum Lunae secundum hanc Theoriam definire velimus, vires erunt spectandae omnes, quibus Luna sollicitatur. Atque inter has vires primaria est ea, qua ad terram utretur, quae si sola adesset, terraque quiesceret, Luna in ellipsi perfecta secundum regulas Keplerianas motum suum circa terram abfolueret. At cum Luna praeterea aequae ac terra ipsa etiam ad solem trahatur, haec vi motus ille regularis non medicocriter perturbabitur: atque haec vis a sole profecta omnium difficultatum, quae in determinatione motus Lunae offenduntur, causa est existimanda. Reliquae enim vires, quibus forte Luna secundum Theoriam Newtoni ad reliquos planetas utregi deberet, tam sunt exiguae, ut effectus inde oriundus merito pro nihilo haberi queat.

Solas ergo vires solis ac terrae in computum ducti oportet, si motum Lunae secundum Theoriam definire velimus, atque cum ex his viribus formulae analyticae fuerint erutae, quae motum Lunae complectantur, omne studium in his formulis ita evolvendis erit impendendum, ut inde ad quodvis tempus propofitum locus Lunae assignari, ac more apud Astronomos solito secundum longitudinem et latitudinem definiti queat. Hinc porro Tabulae Astronomicae pro motu Lunae erunt condensae, quibus omnes inaequalitates tam in longitudine quam in latitudine exhibeantur, ex quibus si pro cuiusvis observationis momento locus Lunae computetur, confusus vel diffusus calculi ab observationibus Theoriam vel confirmabit, vel eius defectum declarabit. Neque tamen Theoria sola huiusmodi Tabulis contruendis sufficit, sed quaedam ele-

menta extrinsecus ab observationibus affirmi oportet, quae sunt 1°. Excentricitas orbitae Lunariss, quae salua theoria vel maior vel minor esse potuisset; pender enim a motu Lunae primitus impresso, quem Theoria non determinat, sed tanquam cognitum assumit. 2°. Locus Lunae medius pro quapiam Epocha proposita, qui pariter ex observationibus est concludendus. 3°. Locus Apogei orbitae Lunariss pro Epocha quadam data. 4°. Tempus periodicum Lunae festundum motum medium, quod pender a distantia Lunae media a Terra, ideoque ex sola Theoria determinari nequit. 5°. Locus nodorum Lunae pro Epocha quadam data: et 6°. denique inclinatio media orbitae Lunariss ad planum Eclipticae.

His autem sex elementis per observationes definitis reliqua omnia, quibus ad locum Lunae pro quouis tempore assignandum opus est, ex sola Theoria sunt petenda; quae primo ad quoduis tempus locum Apogei eiusque ideo motum verum praebere debet, ut inde ex loco Lunae medio eius anomalia media colligi queat. Deinde Theoria quoque omnes correctiones seu Prosthaphaereses, quae loco Lunae medio vel additae vel subtrahae eius locum verum exhibeant, suppediare debet; atque istas correctiones, quae motus inaequalitates appellari solent, partim ab Anomalia media Lunae, partim ab eius Phasi seu elongatione a sole, partimque ab Anomalia solis media pendent, ex quo triplici fonte numerus inaequalitatum in immanentium augetur. Porro etiam Theoria motum nodi eiusque omnes inaequalitates indicare tenetur, ac denique etiam pro quouis tempore orbitae Lunariss veram inclinationem

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ad eclipticam, ut inde eius latitudinem veram eruere liceat.

Cum autem, ut iam innxi, nemo adhuc omnes inaequalitates, quae in motu Lunae reperiuntur, ex Theoria elicerit, ut ex his iudicium ferri possit, quantum haec Theoria cum observationibus conveniat; est nullum est dubium quin discrimen, si quod deprehenderetur, admodum paruum sit futurum: iam pridem haec quaestio ex solo motu Apogei dirimi est coepta, dum alius motus Apogei ex observationibus cognitus magnopere a Theoria discrepare est visus, alii autem etiam hoc loco pulcherrimum consensum Theoriae et veritatis inveniunt. Mirum autem est, ipsam Newtonum nihil circa motum Apogei ex Theoria factuisse, sed eum ex solis observationibus in calculum transfuisse, cum tamen motum nodorum summa sagacitate ex Theoria eliceret, atque veritati consentaneum ostendisset. Cur igitur motum Apogei plane silentio praetererit, nulla alia ratio subesse videtur, nisi quod animaduverterit hunc motum, prout ex Theoria praediret, observationibus parum fore conformem. Ex his enim, quae Newtonus in suo immortalis opere de motu abscondum in genere tradidit, non admodum difficile videtur motum apogei Lunae definire: verum hic praeter expectationem evenit, ut motus apogei annuus vix 20° superans repereretur, cum tamen ex observationibus constet, Apogeam Lunae intervallo vnius anni ultra 40° promoueri.

Sive autem ista motus Apogei quantitas 20° legitime sit ex Theoria derivata, sive minus; consideratio Apogei cuiusdam praebet remedium quaestionem de sufficienti Theo-

Theoriae Newtonianae deciderit. Quamvis enim ex Theoria inaequalitas quaeprimi in ipso motu Lunae aliquot minutis secundis vel etiam primis maior minorem prodiret, quam experientia monstraret, tamen tantilla differentia merito vel levi culpam errori in observationibus, vel vix in approximatione commisso tribueretur; quandoquidem aliunde certum est Theoriam Newtonianam non admodum a veritate recedere. At longe aliter est comparata ratio motus Apogei: quodsi enim vires Lunam sollicitantes tantillum a Theoria Newtoniana discrepent, ut ex his in ipso motu Lunae vix perceptibile discrimen nasceretur, tamen inde in motu Apogei annuo differentia plurimum graduum orti poterit. Quae tanta differentia cum nulli errori vel observationum vel ipsius calculi, siquidem omni cura investigatur, tribui queat, investigatio motus apogei certissimum suppediat criterium iudicandi, utrum quaeprimam Theoria veritati sit consentanea nec ne?

Quodsi ergo calculo rite administrato Theoria Newtoni reperiretur tantum Apogei Lunaris motum exhibere, quantum per observationes deprehenditur, scilicet ultra 40° quotannis; fortius certe argumentum, quo veritas huius Theoriae indubie demonstraretur, defiderari nequit. Sin autem contra eveniat, ut progressio Apogei annua ex Theoria rite derivata nonnulliter a 40° deficiat, hinc certo erit concludendum Theoriam Newtonianam correctione quapiam indigere, neque vires, quibus Luna rite sollicitatur, exactissime huic Theoriae esse conformes. Verum haec ipsa quaeestio, utrum Theoria Newtoniana ad verum apogei Lunae motum perducatur nec ne? est profun-

fundissimae indaginis, atque summam in calculo circumspeditionem ac solertiam requirit. Quaequam enim ex principis generalibus, unde vulgo motus abisum definiti solet, satis luculenter semissis tantum pro motu Apogei Lunae elicatur; tamen quoniam in calculo plures termini, quibus in determinationem motus Lunae ingrediuntur, ob partitatem sunt reiecti, merito dubitatio suboritur, num hi ipsi termini, si eorum ratio esset habita, non istum defectum compensare valuerint? Quin etiam non desinere Geometrae, qui consensum huius Theoriae cum vero Apogei motu demonstrare sunt conati: verum plerumque non difficile erat paralogismum in ipsorum ratiociniis deprehendere. Maximam autem hoc loco attentionem meretur iudicium profundissimi Geometrae Clairaut, qui cum primum validissimis argumentis tenuisset, Newtoni Theoriam non vltra dimidium veri apogei Lunaris motus suppediare, subitico in contrariam abijt sententiam statuens hanc Theoriam elegantissime cum veritate confutare; neque certe tantae perspicaciae Viri pristinae sententia, quam omni studio propugnauerat, recessisse: sed putandus, nisi firmissimis argumentis eo esset adhaesurus.

Cum autem omnes rationes, quae ipsum ad hanc resolutionem impulerint, nondum publicis expoierit, licet at tamen quidem, qui semper contrariae sententiae sui addictus, tantisper arduam hanc quaeestionem eamquam nondum decisam spectare, donec per propriam investigationem inveniret, quid de ea sit statuendum. Posquam enim tanta & longo temporis intervallo plurimum studi in indagandis motus Lunae consummassem, ac variis methodis investigaverim

semper conclusionem Theoriæ Newtonianæ minus fau-
entem esse adeptus; quam tamen pro rite demonstrata
vendicare non erant ausus, propterea quod approxima-
tione essent visus, ac semper suspicio quaedam ratione ter-
minorum præterminis remaneret: nuper in aliam in-
tendi viam hanc investigationem suscipiendi, quæ mihi
multo certior videtur, iam ut per eam nulla dubitatione
interiecta ad veritatem penetrare possidam. Ne autem
si forte Theoriam Newtonianam minus sufficientem in-
tendit, calculum secundum aliam Theoriam de novo in-
stituere cogat, statim meam investigationem in laetiori sen-
su exordiar, viresque quibus Luna ad terram sollicitatur,
non exacte sed proxime tantum quadratis distantiarum re-
ciprocæ proportionales affirmant: deinceps scilicet inno-
tescet, virtum hæc abstrahit a regula Newtoniana locum
habet nec ne? Calculum autem ista adornabo, ut quicquid
euenierit, non solum verum apogei motum assequar, sed
etiam omnes Lunæ inæqualitates inde elicere valeam, quas
deinceps Astronomorum more tabulis complecti licebit.

Primum ergo problema in latissimo significatu con-
cipiam, ut corporis a viribus quibuscunque sollicitati mo-
tum sin inuestigaturus: deinde vires, quibus Luna actu
vixeri censenda est; in calculum introducam; et æquatio-
nes Lunæ motum determinantes exhibebo. Has, porro
æquationes variis modis in alias formas transmutabo, do-
ctæ easse perduxero, ubi ad finem propostum maxime
accommodatas videbuntur: quo cum pervenero, tandem
tam motum Apogei, quam quædam Lunæ inæqualitates
exhibebis deinceps studbo.

CAPUT

DE MOTU CORPORIS A VIRIBUS QUIBUS-
CUNQUE SOLLICITATI.

§. 1.

Quoniam corpus a viribus quibuscunque sollicitari
potimus, fieri potest, ut eius motus non in eo-
dem plano absoletur. Hinc ad ejus motum
per calculum ita representandum, ut ad quodvis tem-
pus verus locus, in quo corpus versabitur, assignari
queat, conveniet corporis motum ad planum quoddam
fixum pro habitu assumum referri. Exhibeat igitur Ta-
bula hoc planum, atque corpus iam videtur extra hoc
planum in puncto L, unde ad planum demittitur per-
pendiculum LM; erique punctum M locus corporis
ad planum relatus. Quod si ergo ad quodvis tempus
propositum hunc corporis locum relatum M, sinulque
eius a plano distantiam LM indicare valeamus, verus
corporis locus L ad hoc tempus innotescet.

§. 2. Ad locum autem puncti M commodius de-
terminandum, assumamus in plano rectam quandam
fixam CQ pro axe, ita ut ducta ex M ad hanc rectam
perpendiculari MP, locus puncti M more apud Geo-
metras recepto per coordinatas orthogonales definiatur.
Assumo ergo porro in axe puncto quodam fixo C,
unde abscissæ C.P computentur, erit P.M applicata
puncto M respondens, & ipsam punctum L. determinat
bicit per tres coordinatas inter se normales CP, PM &
ML.

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APUT

M. L. Cum igitur praesenti temporis momento corpus in L. versari ponatur, vocentur istae tres coordinatae eo spectantes:

$$CP = p; PM = q \text{ et } ML = r$$

elapso autem temporis elemento, quod per d indicemus, coordinatae ternae tum locum corporis indicantes erunt:

$$p + dp; q + dq; \text{ et } r + dr.$$

§. 3. Quaecumque nunc fuerint vires, quibus corpus sollicitatur, eae semper per cognitam virium resolutionem reduci poterunt ad ternas vires secundum directiones ternarum coordinatarum vrgentes. Ponamus ergo vim $\equiv P$, qua corpus in L. secundum directionem ipsi P C parallelam trahitur: eam porro vim $\equiv Q$, quae corpus secundum directionem ipsi M P parallelam trahitur: eamque denique vim $\equiv R$, qua corpus secundum directionem L M sollicitatur. Has sollicitet vires in directas concipio, ut si corpus earum actioni libere obediret, valores coordinatarum p, q, r inde diminuerentur. His positis, ex principis Mechanicae constat, si elementum temporis d pro constanti assumatur, motum corporis his tribus formulis differentio-differentialibus determinari

$$I. dp = -\frac{1}{r} P d r; II. dq = -\frac{1}{r} Q d r; III. dr = -\frac{1}{r} R d r.$$

§. 4. Verum hae coordinatae ad usum astronomicum, eae quem hic potissimum respicimus, non satis sunt accommodatae. Nam si spectatorem in C constitutum assumimus, locus L, vbi corpus cenetur, commodissime

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me per quantitatem rectae C M, et angulum Q C M vna cum angulo M C L represententur: atque si tabula planum eclipticae referat, rectaeque C Q ad principium arietis sit directae, angulus Q C M in Astronomia vocari solet sideris longitudo, angulus M C L vero eius latitudo, et recta C M eius distantia curata. Vocemus ergo porro:

I. Distantiam curatam seu rectam C M = x

II. Longitudinem seu angulum Q C M = ϕ

III. Latitudinem seu angulum M C L = ψ

ac posito constanti sinu toto $\equiv 1$, erunt valores coordinatarum ante adhibitarum:

$$CP = p = x \cos \phi; PM = q = x \sin \phi \& ML = r = x \tan \psi$$

atque distantia corporis vera a puncto C erit C L =

$$x \sec \psi = \frac{x}{\cos \psi}.$$

§. 5. Sumtis nunc differentialibus more consueti obtinebimus:

$$dp = dx \cos \phi - x d\phi \sin \phi; dq = dx \sin \phi + x d\phi \cos \phi$$

$$\text{et } dr = dx \tan \psi + \frac{x d\psi}{\cos^2 \psi}$$

atque hinc denuo differentialibus sumendis reperietur,

$$dip = dx \cos \phi - 2dx d\phi \sin \phi - x d d\phi \sin \phi - x d\phi^2 \cos \phi$$

$$ddq = dx \sin \phi + 2dx d\phi \cos \phi + x d d\phi \cos \phi - x d\phi^2 \sin \phi$$

$$ddr = dx x \tan \psi + \frac{2dx x d\psi}{\cos^3 \psi} + \frac{x d d\psi}{\cos^2 \psi} + \frac{2x d\psi^2 \sin \psi}{\cos^4 \psi}$$

Hinc priores formulae rite combinatae suppediabant sequentes multo concinniores

$$ddp \cos \Phi + ddq \sin \Phi = dx - x d\Phi^2$$

$$ddq \cos \Phi - ddp \sin \Phi = 2 dx d\Phi + x dd\Phi$$

sicque habebitur :

$$dx - x d\Phi^2 = -\frac{x}{2} d\Phi^2 (P \cos \Phi + Q \sin \Phi)$$

$$2 dx d\Phi + x dd\Phi = -\frac{x}{2} d\Phi^2 (Q \cos \Phi - P \sin \Phi)$$

Tertiam vero aequationem deinceps magis tractabilem efficiemus.

§. 6 Manifestum autem est formulam $P \cos \Phi + Q \sin \Phi$ praebere vim ex viribus P et Q compositam, qua corpus in L secundum directionem rectae MC vrigetur, formulam vero alteram $Q \cos \Phi - P \sin \Phi$ exprimere vim ex eadem resolutione secundum directionem MQ ad MC normalem directam. Cum igitur hae duae vires assumtis binis P et Q aequivalent, ponamus esse

I. Vim corpus L secundum MC trahentem = V

II. Vim corpus L secundum MQ trahentem = T

manente tertia vi corpus ad planum normaliter secundum LM vrigente = R. Acque sequentes habebimus aequationes:

$$I. 2 dx d\Phi + x dd\Phi = -\frac{x}{2} T d\Phi^2$$

$$II. dx dx - x d\Phi^2 = -\frac{x}{2} V d\Phi^2$$

$$III. dx tang \psi + \frac{2 dx d\psi}{\cos \psi} + \frac{x dd\psi}{\cos \psi} + \frac{2 x d\psi^2 \sin \psi}{\cos \psi} = -\frac{x}{2} R d\Phi^2$$

§. 7. Quo autem effectum tertiae vis R commodius ad calculum revertemur, more apud Astronomos recepto contempletur planum, in quo corpus durante elemento

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abijem

+ Q

, qua regitur, re vim ad MC assum-

= V

= T

secundum habebit-

i R d\Phi^2

notius os relurante elemento

elemento temporis dt mouetur, et quod simul per punctum C transeat. Hoc igitur planum cum plano assumpto intersectionem alicubi formabit, quae sit recta CS, ac linea nodorum appellari solet; sicque erit SCCL planum orbitae, in qua corpus L praesenti instanti mouetur, et angulus, quo hoc planum SCCL ad planum fixum QCM inclinatur, vocatur inclinatio orbitae ad eclipticam pro tempore praesenti. Cum igitur ex his duabus rebus latitudo sideris desiniri solet, ponamus.

Longitudinem nodi ascendentis seu angulum QCS = π ac inclinationem orbitae SCCL ad eclipticam = ρ atque loco latitudinis ψ has duas quantitates, π et ρ desinire oportebit.

§. 8. Tertia ergo aequatio in duas disperietur, ad quas inveniendas ex M et L ad lineam nodorum CS ducantur normales MN et LN, erique angulus LNM mensura inclinationis orbitae ad eclipticam; ideoque LNM = ρ . Tum vero ob angulum SCM = $\Phi - \pi$ et CM = x erit:

$$CN = x \cos(\Phi - \pi) \text{ et } MN = x \sin(\Phi - \pi)$$

hinc elicietur ML = $x \tan \rho \sin(\Phi - \pi)$, unde prodit tang MCL = $\tan \psi = \tan \rho \sin(\Phi - \pi)$, quae formula inservit latitudini ψ ex cognita inclinatione ρ et loco nodi eiusus longitudine π inveniendae, si quidem iam cognita fuerit longitudo sideris Φ . Quoniam autem si dus elemento temporis dt in eodem plano manet, in differentiatione formulae tang $\psi = \tan \rho \sin(\Phi - \pi)$, quant-

quantitates π et ϱ tanquam constantes spectari poterunt, atque idcirco,

$$\frac{d\psi}{\cos\psi^2} = d\varphi \operatorname{tang} \varrho \cos(\varphi - \pi)$$

§ 9. Interim tamen nihil impedit, quominus in eadem differentiatione quantitates π et ϱ tanquam variables tractemus, quales reuera esse possunt successu temporis; unde oritur haec aequatio:

$$\frac{d\psi}{\cos\psi^2} = \frac{d\varrho}{\cos\varrho^2} \sin(\varphi - \pi) + (d\varphi - d\pi) \operatorname{tang} \varrho \cos(\varphi - \pi)$$

hique valor ipsius $\frac{d\psi}{\cos\psi^2}$ collatus cum praecedente praebebit hanc aequalitatem:

$$\frac{d\varrho}{\cos\varrho^2} \sin(\varphi - \pi) = d\pi \operatorname{tang} \varrho \cos(\varphi - \pi)$$

unde obtinemus $\frac{d\varrho}{\sin\varrho \cos\varrho} = \frac{d\pi \cos(\varphi - \pi)}{\sin(\varphi - \pi)} = \frac{d\pi}{\operatorname{tang}(\varphi - \pi)}$.

Cum iam sit $\frac{d\varrho}{\sin\varrho \cos\varrho} = \frac{d. \operatorname{tang} \varrho}{\operatorname{tang} \varrho^2} = d. l \operatorname{tang} \varrho$, erit

$$d. l \operatorname{tang} \varrho = \frac{d. \operatorname{tang}(\varphi - \pi)}{\operatorname{tang}(\varphi - \pi)}$$

ex quo, si longitudo nodi iam fuerit reperta, sine labore inclinatio ad eclipticam ϱ investigari poterit.

§. 10. Differentiemus formulam primo inuentam $\frac{d\psi}{\cos\psi^2} = d\varphi \operatorname{tang} \varrho \cos(\varphi - \pi)$

iterum, et cum sit $d. \operatorname{tang} \varrho = \frac{d\pi \operatorname{tang} \varrho \cos(\varphi - \pi)}{\sin(\varphi - \pi)}$

erit:

erit:

$$\begin{aligned} \frac{d d \psi}{\cos \psi^2} + \frac{2 d \psi^2 \sin \psi}{\cos \psi^3} &= d d \varphi \operatorname{tang} \varrho \cos(\varphi - \pi) \\ &+ \frac{d \varphi d \pi \operatorname{tang} \cos(\varphi - \pi)^2}{\sin(\varphi - \pi)} - d \varphi (d \varphi - d \pi) \operatorname{tang} \varrho \sin(\varphi - \pi) \\ \text{seu } \frac{d d \psi}{\cos \psi^2} + \frac{2 d \psi^2 \sin \psi}{\cos \psi^3} &= d d \varphi \operatorname{tang} \varrho \cos(\varphi - \pi) \\ &+ \frac{d \varphi d \pi \operatorname{tang} \varrho - d \varphi^2 \operatorname{tang} \varrho \sin(\varphi - \pi)}{\sin(\varphi - \pi)} \end{aligned}$$

qui valores pro ψ in tertia aequatione superiori substitui suppeditebunt:

$$\begin{aligned} d \pi \operatorname{tang} \varrho \sin(\varphi - \pi) + 2 d \pi d \varphi \operatorname{tang} \varrho \cos(\varphi - \pi) + x d d \varphi \operatorname{tang} \varrho \cos(\varphi - \pi) \\ + \frac{x d \varphi d \pi \operatorname{tang} \varrho}{\sin(\varphi - \pi)} - x d \varphi^2 \operatorname{tang} \varrho \sin(\varphi - \pi) &= -\frac{1}{2} R d \varrho^2 \end{aligned}$$

quae transmutetur in hanc:

$$\begin{aligned} (d d \pi - x d \varphi^2) \operatorname{tang} \varrho \sin(\varphi - \pi) + (2 d \pi d \varphi - x d d \varphi) \operatorname{tang} \varrho \cos(\varphi - \pi) \\ + \frac{x d \varphi d \pi \operatorname{tang} \varrho}{\sin(\varphi - \pi)} &= -\frac{1}{2} R d \varrho^2 \end{aligned}$$

§. 11. Commode, hic euenit vt in ista formula illae ipsae expressiones differentio-differentiales $d d \pi - x d \varphi^2$ et $2 d \pi d \varphi - x d d \varphi$ occurrant, quae ex actione duarum reliquarum virium sunt enatae; unde si formularum harum valores aequivalentes $-\frac{1}{2} V d \varrho^2$ et $-\frac{1}{2} T d \varrho^2$ substituiamus, impetrebimus

$$-\frac{1}{2} V d \varrho^2 \operatorname{tang} \varrho \sin(\varphi - \pi) - \frac{1}{2} T d \varrho^2 \operatorname{tang} \varrho \cos(\varphi - \pi) + \frac{x d \varphi d \pi \operatorname{tang} \varrho}{\sin(\varphi - \pi)} = -\frac{1}{2} R d \varrho^2$$

qua differentiale $d \pi$, quo promotio elementaris lineae nodorum indicatur, ita determinabitur, vt sit

$$d \pi = \frac{1}{2} d \varrho^2 \cdot \frac{\sin(\varphi - \pi)}{x d \varphi} (V \sin(\varphi - \pi) + T \cos(\varphi - \pi) - \frac{R}{\operatorname{tang} \varrho})$$

Deinde

Deinde cum sit λ , $l \operatorname{tang} \varrho = \frac{d\pi}{\operatorname{tang}(\varphi - \pi)}$, erit

$$d \operatorname{tang} \varrho = \frac{\operatorname{col}(\varphi - \pi)}{\pi d\varphi} (V \sin(\varphi - \pi) + T \operatorname{col}(\varphi - \pi) - \frac{R}{\operatorname{tang} \varrho})$$

Duas ergo has aequationes loco superioris tertiae, ex qua latitudo ψ inveniri debebat, in calculum introduci conveniet; inuenietis enim π , et ϱ erit $\operatorname{tang} \psi = \operatorname{tang} \varrho \sin(\varphi - \pi)$.

§. 12. Hinc patet lineam nodorum nunquam esse mobilem, quin sinui inclinatio ϱ variationi sit abnoxia. Eadem enim vis $V \sin(\varphi - \pi) + T \operatorname{col}(\varphi - \pi) - \frac{R}{\operatorname{tang} \varrho}$, quae lineae nodorum motum imprimit eius longitudinem π immutando, simul in inclinatione ϱ variationem generat. Nulli autem plane immutationi eam linea nodorum, quam inclinatio erunt subiectae, si vis illa eueniat, quod euenit si media directio omnium virtuum corpus L sollicitantium in ipsam planum δ CL, in quo corpus femel moveri coepit, perpetuo incidat; hincque est casus, quo corpus continuo in eodem plano moveri pergit. Generatim ergo corporis a tribus virtibus V, T, R sollicitati motus quatuor sequentibus aequationibus determinatur.

$$\text{I. } 2 d x d \varphi + \pi d d \varphi = - \frac{1}{2} T d t^2$$

$$\text{II. } d d x - \pi d \varphi^2 = - \frac{1}{2} V d t^2$$

$$\text{III. } d \pi = \frac{1}{2} d t^2, \frac{\sin(\varphi - \pi)}{\pi d \varphi} (V \sin(\varphi - \pi) + T \operatorname{col}(\varphi - \pi) - \frac{R}{\operatorname{tang} \varrho})$$

$$\text{IV. } d. l \operatorname{tang} \varrho = \frac{d \pi}{\operatorname{tang}(\varphi - \pi)}$$

quas ergo quouis casu oblati resolui oportet.

CAPUT

CAPUT II.

INVESTIGATIO VIRIUM LUNARUM SOLLICITANTIIUM.

§. 13.

Cum Lunae motus, qualis ex centro terrae spectaretur, definiti debeat, sit C terrae centrum, ad quod etiam praecipua vis, qua Luna virgetur, directae concipitur; atque tabula exhibeat planum eclipticae, in quo nunc quidem Sol existat in S, Luna vero supra hoc planum versetur in L latitudinem habens borealem, vnde ad planum eclipticae perpendicularum demittatur LM. Hinc ductis rectis CL, CM, CS, itemque CQ initium arctis verius, vnde longitudines computari solent, sunt sequentes denominationes.

1. Longitudo Solis seu angulus ACS = θ
2. Longitudo Lunae seu angulus ACM = φ
3. Latitudo Lunae seu angulus MCL = ψ
4. Distantia Solis a Terra CS = γ
5. Distantia Lunae a Terra curvata CM = π

§. 14. Sit iam AM proleccio orbitae lunaris in planum eclipticae; ac planum, in quo Luna nunc movetur, per centrum terrae ductum, planum eclipticae interfecit secundum rectam CS, quae lineam nodorum pro tempore praefenti exhibebit: ac terminus δ quidem nodum ascendentem referet, siquidem lunam secundum regionem AM promoveri ponamus. Quod si ergo porro vocemus

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6. Lon-

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6. Longitudinem nodi asc: $ACR = \pi$

7. Incl. orbitae Lunae ad eclipticam $= \varrho$

hinc latitudo Lunae geocentrica ita definitur, vt fit tang $\psi = \text{tang. sin}(\varphi - \pi)$. Vnde incrementum latitudinis $d\psi$ commode assignabitur, cum fit, vt supra vidimus $d \text{ tang } \psi = \frac{d\psi}{\text{cof } \psi} = d\varphi \text{ tang } \varrho \text{ cof}(\varphi - \pi)$: ac

praeterea ex motu nodi cognitio variatio inclinationis ita definitur, vt fit $d \text{ tang } \varrho = \frac{d\pi \text{ tang } \varrho}{\text{tang}(\varphi - \pi)}$, seu $d\varrho = \frac{d\pi \text{ sin } \varrho \text{ cof } \varrho}{\text{tang}(\varphi - \pi)}$.

§. 15. Cum nunc primum Luna ad centrum terrae C secundum directionem LC attrahatur, fit haec vis $= M$. Deinde fit vis, qua Luna ad solem S vrgetur secundum LS $= N$; atque his duabus viribus Luna proprie vrgeri censenda est. Praeterea vero cum Terra ipsa, ad quam motum Lunae referimus, in motu vertetur, ut eam tanquam quietentem considerare queamus, non solum motum Terrae, sed etiam vires, quibus Terra vrgetur, toti mundo secundum plagas oppositas imprimi concipiamus. Sit igitur vis qua Terra ad Solem vrgetur $= S$, & vis qua ad Lunam trahitur $= L$, his viribus contrario modo in lunam translatis, Luna sequentibus viribus sollicitata habebitur

1. Secundum directionem LC vi $= M + L$

2. Secundum directionem LS vi $= N$

3. Secundum directionem MR ipsi

SC parallelam vi $= S$.

§. 16. Hunc

§. 16. Nunc primo has vires ad terras directiones supra assumas MC, MQ et LM reducemus; ac primo quidem vis $M + L$ dabit

pro directione MC vim $= (M + L) \text{ cof } \psi$

pro directione LM vim $= (M + L) \text{ sin } \psi$

Secunda vis N vero dabit

pro directione LM vim $= \frac{LM}{LS} \cdot N$

pro directione MS vim $= \frac{MS}{LS} \cdot N$

at haec vltimus resoluta duca M' ipsi CS parallela dabit:

pro directione MC vim $= \frac{MC}{LS} \cdot N$

pro directione M' vim $= \frac{CS}{LS} \cdot N$

Haec postrema a vi tertia S subtrahita relinquet vim

$S - \frac{CS}{LS} \cdot N$, qua Luna secundum directionem MR sol-

licitatur, quae ob angulum CMR $= SCM = \varphi - \theta$ dabit

pro directione MC vim $= (S - \frac{CS}{LS} \cdot N) \text{ cof}(\varphi - \theta)$

pro directione M q vim $= (S - \frac{CS}{LS} \cdot N) \text{ sin}(\varphi - \theta)$

vbi directio M q contraria est directione MQ.

§. 17. His iam viribus cum ternis inito assumtis V, T et R comparandis, inueniemus pro his viribus sequentes valores:

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in $\varrho \text{ cof } \varrho$

$\varrho (\varphi - \pi)$.

in terrae

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non so-

luta ipsa,

etur, ut

sec vis

etur se-

ma pro-

ra ipsa,

etur, ut

non so-

luta ipsa,

etur, ut

1. pro directione MC vim V =

$$(M+L) \operatorname{cof} \psi + \frac{MC}{L S} \cdot N + (S - \frac{CS}{L S} \cdot N) \operatorname{cof}(\varphi - \theta)$$

2. pro directione MQ vim T = $-(S - \frac{CS}{L S} \cdot N) \operatorname{fin}(\varphi - \theta)$

3. pro directione LM vim R = $(M+L) \operatorname{fin} \psi + \frac{LM}{L S} \cdot N$.

Cum nunc sit CM = x, CS = y, et angulus SCM = φ - θ; erit MS = $\sqrt{(x^2 - 2xy \operatorname{cof}(\varphi - \theta) + y^2)}$, et ob LM = x tang ψ erit LS = $\sqrt{(y^2 - 2xy \operatorname{cof}(\varphi - \theta) + x^2 \sec^2 \psi^2)}$, quae distantia Solis a Luna LS breuitatis gratia ponatur = n, vt sit n = $\sqrt{(y^2 - 2xy \operatorname{cof}(\varphi - \theta) + x^2 \sec^2 \psi^2)}$. His ergo valoribus introductis erunt vires nostrae:

$$1. V = (M+L) \operatorname{cof} \psi + \frac{N x}{n} + S \operatorname{cof}(\varphi - \theta) - \frac{N y}{n} \operatorname{cof}(\varphi - \theta)$$

$$2. T = -S \operatorname{fin}(\varphi - \theta) + \frac{N y}{n} \operatorname{fin}(\varphi - \theta)$$

$$3. R = -(M+L) \operatorname{fin} \psi + \frac{N x \operatorname{tang} \psi}{n}$$

§. 18. Quia nunc est tang ψ = tang ρ fin(φ - π) et fin ψ = tang ψ cof ψ erit:

$$\frac{R}{\operatorname{tang} \rho} = (M+L) \operatorname{cof} \psi \operatorname{fin}(\varphi - \pi) + \frac{N x \operatorname{fin}(\varphi - \pi)}{n}$$

tum vero habebitur

$$V \operatorname{fin}(\varphi - \pi) + T \operatorname{cof}(\varphi - \pi) = (M+L) \operatorname{cof} \psi \operatorname{fin}(\varphi - \pi) + \frac{N x \operatorname{fin}(\varphi - \pi)}{n}$$

$$+ S \operatorname{cof}(\varphi - \theta) \operatorname{fin}(\varphi - \pi) - \frac{N y \operatorname{cof}(\varphi - \theta) \operatorname{fin}(\varphi - \pi)}{n}$$

$$- S \operatorname{fin}(\varphi - \theta) \operatorname{cof}(\varphi - \pi) + \frac{N y \operatorname{fin}(\varphi - \theta) \operatorname{cof}(\varphi - \pi)}{n}$$

quae ob cof(φ - θ) fin(φ - π) - fin(φ - θ) cof(φ - π) = fin(φ - π), dat

V fin

$$V \operatorname{fin}(\varphi - \pi) + T \operatorname{cof}(\varphi - \pi) - \frac{R}{\operatorname{tang} \rho} = S \operatorname{fin}(\theta - \pi) - \frac{N y}{n} \operatorname{fin}(\theta - \pi)$$

ex quo aequationes motum Lunae continentes erunt:

$$I. 2dx d\varphi + x d\varphi^2 = -\frac{1}{2} dt^2 \left(\frac{N y}{n} - S \right) \operatorname{fin}(\varphi - \theta)$$

$$II. dx^2 - x d\varphi^2 = -\frac{1}{2} dt^2 \left((M+L) \operatorname{cof} \psi + \frac{N x}{n} - \left(\frac{N y}{n} - S \right) \operatorname{cof}(\varphi - \theta) \right)$$

$$III. dx = -\frac{1}{2} dt^2 \cdot \frac{\operatorname{fin}(\varphi - \pi) \operatorname{fin}(\theta - \pi)}{x d\varphi} \left(\frac{N y}{n} - S \right)$$

$$IV. dx / \operatorname{tang} \rho = \frac{dx}{\operatorname{tang}(\varphi - \pi)}$$

vbi θ - π exprimit angulum ∟ CS seu distantiam Solis a nodo ascendente.

§. 19. Jam secundum Theoriam Newtoni, si massam Terrae ponamus = c ac Lunae = c, ob distantiam CL = $\frac{x}{\operatorname{cof} \psi}$, foret vis M = $\frac{c \operatorname{cof} \psi^3}{x^2}$ et vis L = $\frac{C \operatorname{cof} \psi^2}{x^2}$,

sicque vis tota M+L = $(c + C) \cdot \frac{\operatorname{cof} \psi^2}{x^2}$. Quo autem,

si forte haec Theoria insufficiens deprehendatur, rem generalius complectarur, ponamus hanc vim:

$$M + L = (c + C) \operatorname{cof} \psi^2 \left(\frac{1}{x^2} - \frac{1}{bl} \right)$$

vbi terminus $\frac{1}{bl}$ defectum huius vis a Theoria Newtoniana exhibeat; qui cum sit minimus, pro constanti haberi poterit saltem pro exigua variabilitate, quam distantia x subit. Vim autem Solis exacte Theoriae Newtonianae conformem assumere poterimus; quoniam etiam si inde recederet, differentia non solum foret

quam minima, sed quia pro Luna aequae discreparet ac pro Terra, in nostris formulis nullius plane esset momenti.

§ 20. Posita ergo Solis massa = \odot , erit vis, qua Terram ad se attrahit $S = \frac{\odot}{y^2}$, vis autem qua Lunam

ad se trahit $N = \frac{\odot}{\#^2}$. His ergo valoribus virium in calculum indutis, motus Lunae ex quantor sequentibus aequationibus determinari debet:

$$I. 2dx d\varphi + x d\varphi^2 = -\frac{1}{2} d\varphi^2 \left(\frac{\odot y}{\#^2} - \frac{\odot}{y^2} \right) \sin(\varphi - \theta)$$

$$II. ddx - x d\varphi^2 = -\frac{1}{2} d\varphi^2 (\delta + C) \cos \psi^2 \left(\frac{1}{x^2} - \frac{1}{b^2} \right) - \frac{1}{2} d\varphi^2 \left(\frac{\odot x}{\#^2} - \frac{\odot y}{\#^2} \right) \cos(\varphi - \theta) + \frac{\odot y}{\#^2} \cos(\varphi - \theta) + \frac{\odot}{y^2} \cos(\varphi - \theta)$$

$$III. d\pi = -\frac{1}{2} d\varphi^2 \cdot \frac{\sin(\varphi - \pi) \sin(\theta - \pi)}{x d\varphi} \left(\frac{\odot y}{\#^2} - \frac{\odot}{y^2} \right)$$

$$IV. d. l \tan \varphi = \frac{d}{\pi} \tan(\varphi - \pi)$$

Hic iam primum curandum est, ut elementum temporis, quod est quantitas heterogenea, ex calculo eliminemus; id quod commodissime fiet, si motum medium solis vixote temporis proportionalem, loco temporis in calculum introducemus.

§ 21. Cum igitur etiam motus Solis in his aequationibus sit ratio habenda, eum prius inuestigemus: et quoniam pro terra quiescente Sol a sola vi $\frac{\odot}{y^2}$ ad terram

ram sollicitari concipiendus est, si formulas pro luna inuenas ad solem accommodemus, obtinebimus:

$$2 dy d\theta + y d\theta^2 = 0$$

$$dd y - y d\theta^2 = -\frac{1}{2} d\varphi^2 \cdot \frac{\odot}{y^2}$$

si iam distantiam Solis a terra mediam ponamus = b eiusque anomaliam mediam = q ; casu quo excentricitas orbitae solaris esset nulla, foret semper $y = b$ & $d\theta = dq$; vnde altera aequatio dabit $-b dq^2 = -\frac{1}{2} d\varphi^2 \cdot \frac{\odot}{b^2}$. Quare loco elementii temporis $d\varphi$ elementum anomaliae mediae solis ita in calculum introduci debet, ut vbiq; loco $\frac{1}{2} d\varphi^2$ scribatur $\frac{b^2 dq^2}{\odot}$, id quod tam in his formulis pro Sole, quam in superioribus pro Luna fieri poterit.

§ 22. Cum iam b denotet distantiam solis a terra mediam, sit eius vera distantia $y = b \omega$, et anomaliam eius vera = s , erit $d\theta = ds$, quandoquidem a motu apogei solis animum abstrahimus. Hinc itaque erit

$$2 d\omega ds + \omega ds^2 = 0$$

$$dd \omega - \omega ds^2 = -\frac{dq^2}{\omega \odot},$$

quarta prior integrata dat $\omega ds = C dq$ ob dq constans, ideoque $\omega ds^2 = \frac{C C dq^2}{\omega^3}$; qui valor in altera aequatione substituitur praebet,

$$dd \omega = \frac{C C dq^2}{\omega^3} - \frac{dq^2}{\omega \odot}.$$

quae

que per $2d\omega$ multiplicata et integrata dat:

$$\frac{d\omega^2}{dq^2} = D - \frac{CC}{\omega\omega} + \frac{2}{\omega}$$

$$\text{vnde fit } dq = \sqrt{\frac{\omega d\omega}{(D\omega\omega + 2\omega - CC)}}$$

$$\text{ac proinde } ds = \frac{\omega \sqrt{(D\omega\omega + 2\omega - CC)}}{C d\omega}$$

§. 23. Quoniam autem hinc valores finiti haud difficulter deduci possent, tamen alia vtar methode, quae in motu Lunae maiorem praestabit utilitatem. Inuento autem $\omega\omega ds = C dq$, alteram aequationem ita transformo, vt elementi constantis dq ratio non amplius habeatur:

$$dq \cdot d \frac{d\omega}{dq} - \omega ds^2 = r \frac{dq^2}{\omega\omega}$$

Sit nunc $\omega = \frac{1}{u}$, vt habeat $ds = C u u dq$, et $d\omega$

$$= -\frac{du}{u^2}, \text{ et ob } dq = \frac{ds}{C u u} \text{ erit } \frac{d\omega}{dq} = -\frac{C du}{ds}; \text{ hinc}$$

$$\text{sumto iam elemento } ds \text{ constante, erit}$$

$$\frac{-d^2s}{C u u} \cdot \frac{C d du}{ds} - \frac{ds^2}{u} = -\frac{C C u u}{ds^2} \text{ seu}$$

$$d du + u ds^2 = \frac{ds^2}{CC}$$

vnde statim elicitur $u = \frac{1 - e \cos f}{CC}$, vbi e excentricitatem orbis solaris indicabit.

§. 24. Hinc porro habebitur $\omega = \frac{CC}{1 - e \cos f}$, et $r = \frac{CC b}{1 - e \cos f}$, anomalia vera s ab apogeo computata; vnde distantia apogei

apogei a terra posito $r = 0$ erit $= \frac{CC b}{1 - e}$, et distantia perigei posito $r = 180^\circ$ prodit $= \frac{CC b}{1 + e}$; siquae distantia media fiet $= \frac{CC b}{1 - e e}$, quae cum per hypothesea aequalis esse debeat ipsi b , statim oportet $CC = 1 - e e$: hincque erit

$$y = \frac{b(1 - e e)}{1 - e \cos f} \text{ et } \omega = \frac{1 - e e}{1 - e \cos f}$$

Porro autem aequato $\omega\omega ds = C dq$ $\sqrt{(1 - e e)}$ abf. bit in hanc:

$$dq = \frac{(1 - e e)^{\frac{3}{2}} ds}{(1 - e \cos f)^2} \text{ et } q = \int \frac{(1 - e e)^{\frac{3}{2}} ds}{(1 - e \cos f)^2}$$

ex qua, vt satis constat, vel data anomalia vera s inueniri potest anomalia media q , vel viceffim. His itaque formulis motum Solis continentibus in dæterminacione motus Lunae vtarur.

hinc

§. 25. Primo ergo loco $\frac{1}{2} ds^2$ vbiq; scribamus $\frac{ds ds}{dq^2}$ et $b\omega$ loco y , quo factis nostrae aequationes fient

I. $2 dx d\phi + x dd\phi = -b ds dq = \left(\frac{b\omega}{u^2} - \frac{1}{b\omega u}\right) \sin(\phi - \theta)$

II. $ddx - x dd\phi^2 = -\left(\frac{b + C}{b^2} b^2 ds^2\right) \cos^2 \psi = \left(\frac{1 - e}{b\omega} - \frac{1}{b\omega}\right)$

III. $dx = \frac{b ds dq^2}{x d\phi} \frac{\sin(\phi - \theta) \sin(\theta - \psi)}{\sin(\psi - \theta)} \left(\frac{b\omega}{u^2} - \frac{1}{b\omega u}\right)$

Ponatur porro $u = b v$, adque in calculum quoque introducta.

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ducatur distantia media lunae a terra, quae sit = a , positio-
que $x = az$, prodibit:

$$I. \ 2dzd\phi + 2dd\phi = \frac{bdq^2}{a} \left(\frac{\omega}{\omega^3} - \frac{1}{a\omega} \right) \sin(\phi - \theta)$$

$$II. \ d dz - 2d\phi^2 = \frac{(\xi + \zeta) b^3}{a^3} dq^2 \cos^2 \psi^2 \left(\frac{1}{2z} - \frac{aa}{bb} \right) \\ + \frac{bdq^2}{\omega^3} + \frac{b\omega dq^2 \cos(\phi - \theta)}{a\omega^3} - \frac{bdq^2 \cos(\phi - \theta)}{a\omega\omega}$$

$$III. \ d\pi = \frac{bdq^2}{a^2 d\phi} \sin(\phi - \pi) \sin(\theta - \pi) \left(\frac{\omega}{\omega^3} - \frac{1}{a\omega} \right)$$

§. 26. Ponamus nunc ad abbreviandum:

$$\frac{(\xi + \zeta) b^3}{a^3} = m; \quad \frac{(\xi + \zeta) b^3}{a^2 b} = \mu, \text{ seu } \mu = \frac{maa}{bb}$$

quarum litterarum valores m et μ per observationes defini-
nti debent; tum vero sit $\frac{a}{b} = y$, quae est quantitas val-
de parva a parallaxi solis pendens. Hisque valoribus in-
troducitis, sequationes nostrae sequentes induent formas;

$$I. \ 2dzd\phi + 2dd\phi = \frac{1}{y} dq^2 \left(\frac{\omega}{\omega^3} - \frac{1}{a\omega} \right) (\sin \phi - \theta)$$

$$II. \ d dz - 2d\phi^2 = \frac{m dq^2 \cos^2 \psi^2}{2z} + \mu dq^2 \cos^2 \psi^2$$

$$+ \frac{bdq^2}{\omega^3} + \frac{1}{y} dq^2 \left(\frac{\omega}{\omega^3} - \frac{1}{a\omega} \right) \cos(\phi - \theta)$$

$$III. \ d\pi = \frac{1}{y} dq^2 \sin(\phi - \pi) \sin(\theta - \pi) \left(\frac{\omega}{\omega^3} - \frac{1}{a\omega} \right)$$

$$IV. \ d / \text{tang } \varrho = \frac{d\pi}{\text{tang}(\phi - \pi)}$$

§. 27.

§. 27. Cum iam posterimus:

$$x = az; \ y = b\omega; \ v = \frac{a}{b} \text{ et } \theta = \frac{a^2}{b^2}$$

erit $u = \sqrt{(bb\omega\omega - 2ab\omega z \cos(\phi - \theta) + aaz z \sec. \psi^2)}$
atque $v = \sqrt{(\omega\omega - 2v\omega z \cos(\phi - \theta) + v v z z \sec. \psi^2)}$
vbi notandum est quantitates ω , z et r ex motu solis ita
inter se pendere, ut sit

$$\omega = \frac{1 - \epsilon t}{1 - \epsilon \cos r} \text{ et } dq = \frac{(1 - \epsilon t)^{\frac{3}{2}} dt}{\sqrt{(1 - \epsilon^2)}}$$

ita ut huic ad datum quodvis tempus, tam valor ipsius ω
quam anomaliae verae r determinari possit. Modum autem
has formulas ad calculum reuocandi hic non trado, quia
eum alias fuis iam expofui: hoc solum hic notari con-
ueniet, excentricitatis orbitae solaris valorem ex observa-
tionibus colligi, $\epsilon = 0, 01680$.

§. 28. Nunc attingam vltimus progressi quatenus,
valorem irrationalem ipsius v tolli conueniet, quod facile
per seriem praestabitur maxime conuergentem, ob v fra-
ctionem valde parvam; summa enim parallaxi solis = $12''$,
quia parallaxis lunae media est = $3380''$, erit $\frac{a}{b} = \frac{1}{295}$
= $\frac{1}{295}$. Hinc sufficit seriei illius conuergentis,
quam reperimus, aliquot tantum terminos ab initio as-
sumisse; quia reliqui ob paruitatem continuo magis cre-
scentem tuto omiti poterunt. Cum autem angulus $\phi - \theta$,
qui distantiam solis a luna secundum longitudinem deno-
tat, in hac resolutione frequentissime occurret, breuitatis
gratia Ponamus $\phi - \theta = \eta$
ita ut pro v sequentem habeamus valorem irrationalem
 $v = \sqrt{(\omega\omega - 2v\omega z \cos \eta + v v z z \sec. \psi^2)}$.

§. 29.

§. 29. Quoniam ergo in nostris formulis occurrunt
 $\frac{1}{\omega^3}$ ob $\frac{1}{\omega^3} = (\omega \omega^{-2} \omega \omega^2 \cos \eta + \nu \nu z \sec \psi^2)^{-\frac{2}{3}}$, nascemur

$$\frac{1}{\omega^3} = \frac{1}{\omega^3} + \frac{3\nu z \cos \eta}{\omega^4} - \frac{3\nu z z \sec \psi^2}{2\omega^5} + \frac{15\nu z z^2 \cos \eta^2}{2\omega^5}$$

ubi terminos altiores ipsius ν potestates innotuentes sine
 haesitatione reicere possumus; in ipsis aequationibus au-
 tem tantum in prima ipsius ν potestate subsistemus. Ha-
 bebimus ergo:

$$\frac{1}{\omega^3} \left(\frac{\omega}{\omega^3} - \frac{1}{\omega \omega} \right) = \frac{3z \cos \eta}{\omega^4} + \frac{3\nu z z}{2\omega^4} (5 \cos \eta^2 - \sec \psi^2) \text{ seu}$$

$$\frac{1}{\omega^3} \left(\frac{\omega}{\omega^3} - \frac{1}{\omega \omega} \right) = \frac{3z \cos \eta}{\omega^4} + \frac{3\nu z z}{4\omega^4} (5 + 5 \cos 2\eta - 2 \sec \psi^2)$$

hincque porro:

$$\frac{1}{\omega^3} \left(\frac{\omega}{\omega^3} - \frac{1}{\omega \omega} \right) \sin(\varphi - \theta) = \frac{3z \sin 2\eta}{2\omega^4} + \frac{3\nu z z}{8\omega^4} (5 \sin \eta + 5 \sin 3\eta - 4 \sin \eta \sec \psi^2)$$

$$\frac{1}{\omega^3} \left(\frac{\omega}{\omega^3} - \frac{1}{\omega \omega} \right) \cos(\varphi - \theta) = \frac{3z}{2\omega^4} (1 + \cos 2\eta) + \frac{3\nu z z}{8\omega^4} (5 \cos \eta + 5 \cos 3\eta - 4 \cos \eta \sec \psi^2)$$

$$\text{hincque } \frac{z}{\omega^3} = \frac{z}{\omega^3} + \frac{3\nu z z}{\omega^4} \cos \eta$$

§. 30. Subsistamus hos valores in nostris aequa-
 tionibus atque obtinebimus:

$$I. 2d^2 d\varphi + zd^2 \varphi = -dg^2 \left(\frac{3z \sin 2\eta}{2\omega^4} + \frac{3\nu z z}{8\omega^4} (5 \sin \eta + 5 \sin 3\eta - 4 \sin \eta \sec \psi^2) \right)$$

$$II. ddz - zd^2 \varphi = -\frac{m d g^2 \cos \psi^2}{z} + \frac{\mu d g^2 \cos \psi^2}{z} + \frac{z d g^2}{2\omega^3} + \frac{3z d g^2}{2\omega^3} \cos 2\eta$$

$$+ \frac{3\nu z d g^2}{8\omega^4} (7 \cos \eta + 5 \cos 3\eta - 4 \cos \eta \sec \psi^2)$$

III. $d\pi$

s occurrunt

meissemur

$$\frac{\nu z z}{\omega^5} \cos \eta^2$$

ientes sine
 onibus au-
 nus. Ha-

ic ψ^2) seu

-2 $\sec \psi^2$)

1 $\eta \sec \psi^2$)

ost $\sec \psi^2$)

is aequa-

1 $\eta \sec \psi^2$)

$$\frac{d g^2}{\omega^3} \cos 2\eta$$

ic ψ^2)

III. $d\pi$

$$III. d\pi = -\frac{d g^2}{2d} \sin(\varphi - \pi) \sin(\theta - \pi) \left(\frac{3z \cos \eta}{\omega^3} + \frac{3\nu z z}{4\omega^4} (5 + 5 \cos 2\eta - 2 \sec \psi^2) \right)$$

$$IV. d / \text{tang } \varphi = \frac{d}{\text{tang}(\varphi - \pi)}$$

Hic iam observare licet, cum angulus ψ nunquam fere
 5° superet, eiusque secans nominis in terminis iam per ν
 multiplicatis, ac propterea respectu reliquorum valde par-
 vis occurrat, sine vilius erroris sensibilibus metu in his ter-
 minis poni posse $\sec \psi = 1$.

§. 31. Deinde ut etiam ex maioribus terminis \cos
 ψ eliminemus; consideremus formulam $\text{tang } \psi = \text{tang } \varphi$
 $\sin(\varphi - \pi)$, erique $\sec \psi = \frac{1}{\cos \psi} = \sqrt{1 + \text{tang}^2 \sin(\varphi - \pi)}$

Hinc ergo habebimus:

$$\cos \psi^2 = (1 + \text{tang } \varphi^2 \sin(\varphi - \pi)^2)^{-\frac{1}{2}}$$

et cum $\text{tang } \varphi^2$ nunquam fere fractionem $\frac{1}{2}$ superet
 erit satis exacte:

$$\cos \psi^2 = 1 - \frac{1}{2} \text{tang } \varphi^2 \sin(\varphi - \pi)^2 \text{ vel etiam}$$

$$\cos \psi^2 = 1 - \frac{1}{2} \text{tang } \varphi^2 + \frac{1}{2} \text{tang } \varphi^2 \cos 2(\varphi - \pi)$$

qui valor pro $\cos \psi^2$ in termino maiore $\frac{m d g^2 \cos \psi^2}{z}$ sub-
 stitui potest: in altero autem termino $\frac{\mu d g^2 \cos \psi^2}{z}$
 quia per se est valde parvus, atque adeo secundum
 Theoriam Newtoni evanesceret, nihil impedit, quo mi-
 nus loco $\cos \psi^2$ scribamus unitatem.

D 3

§. 31. Hoc

§. 32. Hoc ergo modo si aequationes nostras a consideratione latitudinis Lunae ψ liberemus ad sequentes perveniemus aequationes:

I. $2dd\psi + zd\psi = -dq^2 \left(\frac{3z\sin 2\eta}{2\omega^3} + \frac{3vz^2}{8\omega^4} (\sin \eta + 5\sin 3\eta) \right)$

II. $ddz - zd\psi = -\frac{ndq^2}{z} (1 - \frac{1}{2}\text{tang}^2 \eta + \frac{1}{2}\text{tang}^2 \eta \cos 2(\Phi - \pi)) + ndq^2 + \frac{2dq^2}{2\omega^3} + \frac{3zddq^2}{2\omega^3} \cos 2\eta + \frac{3vzddq^2}{8\omega^4} (3\cos \eta + 5\cos 3\eta)$

III. $dn = -\frac{dq^2}{zd\psi} (\sin(\Phi - \pi) \sin(\theta - \pi)) \left(\frac{3z\cos \eta}{\omega^3} + \frac{3vz^2}{4\omega^4} (3 + 5\cos 2\eta) \right)$

IV. $d. l \text{ tang } \eta = \frac{d}{\text{tang}(\Phi - \pi)}$

Nunc igitur in hoc erit incumbendum, ut ex his quatuor aequationibus omnia motus phaenomena, quae in Luna secundum Theoriam adeste debent, follicite eruantur, atque tum cum observationibus conferantur.

ostras a sequen-

$(\sin 3\eta)$

$) + ndq^2$

$- \cos 3\eta)$

$\cos 2\eta)$

is quae in
quae in
ie eru-
ur.

CAPUT III.

INTRODUCTIO ANOMALIAE VERAE LUNAE IN PRAECEDENTES AEQUATIONES.

§. 33.

Quoniam nostra quaestio circa Lunam versatur, loco anomaliae mediae solis, quam pro tempore in calculum introduximus, magis conveniet motu Lunae medio vii, qui eidem tempori est proportionalis. Verum ex sequentibus patebit calculum commodiorem reddi, si loco motus medi adhibeamus anomaliam Lunae medianam, cuius incrementa eidem tempori sunt proportionalia. Sit itaque ad datum tempus anomalia media Lunae $= p$; et cum eius incrementum dp ad incrementum anomaliae mediae solis eodem tempusculo acceptum datum ac per observationes cognitam teneat rationem, ponamus $dp = ndq$. Tabulae autem Astronomicae pro intervallo 365 dierum praebent: Motum anomaliae mediae Solis II, 29°, 44', 39" = 1295079⁶/₁₀ Motum anomaliae mediae Lunae

13^{Nov.} 29, 28°, 43' 13" = 17167393⁶/₁₀

Vnde sic $n = \frac{17167393}{1295079} = 13, 25586$

§. 34. Posito ergo $\frac{dp}{n}$ loco dq , aequationes nostrae erunt

I. $2dd\psi + zd\psi = -\frac{dp^2}{n^2} \left(\frac{3z\sin 2\eta}{2\omega^3} + \frac{3vz^2}{8\omega^4} (\sin \eta + 5\sin 3\eta) \right)$

II. ddz

II. $ddx - zd\phi^2 = \frac{m d p^2}{n n z z} (1 - \frac{1}{2} \text{tang } \varphi^2 + \frac{1}{2} \text{tang } \varphi^2 \text{ cof } 2(\phi - \pi)) + \frac{h d p^2}{n n} + \frac{z d p^2}{2 z^2 \omega^3} + \frac{3 z d p^2}{2 m^2 \omega^3} \text{cof } 2 \eta + \frac{3 m z d p^2}{8 m n \omega^4} (\text{scof } \eta + \text{scof } 3 \eta)$

III. $d\pi = \frac{-d p^2}{m n : d\phi} \sin(\phi - \pi) \sin(\theta - \pi) \left(\frac{3 z \text{cof } \eta}{\omega^3} + \frac{3 m z z}{4 \omega^4} (3 + \text{scof } 2 \eta) \right)$

IV. $d \text{ tang } \varphi = \frac{d \pi}{\text{tang}(\phi - \pi)}$

atque hic elementum $d p$ assumtum est constans: simili autem patet terminos, qui per $m n$ sunt divisi, prae ceteris satis esse parvos, cum sit $m n = 175, 71795$. Quae circumstantia sequentes approximationes non mediocriter adiuuabit.

§. 35. Nunc antequam ulterius progrediamur, aequationem primam per z multiplicemus, atque integratione in priori parte infinitum obtinebimus

$$z z d\phi = C d p - \frac{d p}{m n} \int d p \left(\frac{3 z^2 \sin 2 \eta}{2 \omega^3} + \frac{3 m z^2}{8 \omega^4} (\sin \eta + \text{scof } 3 \eta) \right)$$

ponamus breuius gratia hoc membrum integrale

$$\int d p \left(\frac{3 z^2 \sin 2 \eta}{2 \omega^3} + \frac{3 m z^2}{8 \omega^4} (\sin \eta + \text{scof } 3 \eta) \right) = S$$

quod integrale, ne introductio constans incertitudinem pariat, iam capi assumo, ut nulla terminum mere constantem contineat, quippe qui iam in C esset comprehensus. Hoc ergo circa determinationem integratione probe observato, erit $z z d\phi = d p \left(C - \frac{S}{m n} \right)$: vbi terminus S aequabilem artatum descriptionem, quam Regula Kepleri in planetis p̄maris infert, perturbat; est enim

enim $\frac{1}{2} z z d\phi$ elementum areae descriptae, quod in ipsi C $d p$ esset aequale, tempori exacte esset proportionale.

§. 36. Cum igitur sit $d\phi = \frac{d p}{z z} \left(C - \frac{S}{m n} \right)$, erit

$$z d\phi^2 = \frac{d p^2}{z^3} \left(C C - \frac{2}{m n} C S + \frac{1}{m^2} S S \right), \text{ quo valore substituto reliquae nostrae aequationes sequentes induent formas:}$$

II. $ddx = \frac{d p^2}{z^3} \left(C C - \frac{2}{m n} C S + \frac{1}{m^2} S S \right)$

$$- \frac{m d p^2}{n n z z} \left(1 - \frac{1}{2} \text{tang } \varphi^2 + \frac{1}{2} \text{tang } \varphi^2 \text{ cof } 2(\phi - \pi) \right) + \frac{h d p^2}{n n} + \frac{z d p^2}{2 m \omega^3} + \frac{3 z d p^2}{2 m n \omega^3} \text{cof } 2 \eta + \frac{3 m z d p^2}{8 m n \omega^4} (\text{scof } \eta + \text{scof } 3 \eta)$$

III. $d\pi = - \frac{z d p}{C m n - S} \sin(\phi - \pi) \sin(\theta - \pi) \left(\frac{3 z \text{cof } \eta}{\omega^3} + \frac{3 m z z}{4 \omega^4} (3 + \text{scof } 2 \eta) \right)$

et quarta manet $d \text{ tang } \varphi = \frac{d p}{\text{tang}(\phi - \pi)}$ vt ante.

Eo igitur pertingimus, ut inuestigari oporteat quantitates z, π et φ , quibus inuentis obtinebitur ϕ ex formula primam eruta. Cum autem sic $d\eta = d\phi - d\theta$, ob $d\theta = d s = \frac{d q V(1 - e^2)}{\omega \omega}$ $= \frac{d p V(1 - e^2)}{n \omega \omega}$, erit $d\eta = \frac{d p}{z z} \left(C - \frac{S}{m n} \right) - \frac{d p V(1 - e^2)}{n \omega \omega}$. Tum vero est via vidimus $\omega = \frac{1 - e^2}{1 - e \text{cof } \varphi^2}$ vnde et huius differentiale ad $d p$ reduci poterit.

§. 37. Si hunc calculum profequi vellemus, tota inuestigatio tandem eo rediret, vt definiretur quantum longi-

) + $\frac{h d p^2}{n n} + \frac{z d p^2}{2 z^2 \omega^3} + \frac{3 z d p^2}{2 m^2 \omega^3} \text{cof } 2 \eta + \frac{3 m z d p^2}{8 m n \omega^4} (\text{scof } \eta + \text{scof } 3 \eta)$
 : simili
 e ceteris
 Quae
 : diocri-
 ur, ac
 ntegra-
 (sin 3 η)
 e
 = S
 idinem
 e con-
 impre-
 ationis
 si ter-
 n Re-
 ; est
 enim

E

longitudo Lunae vera ab eius longitudine media, quae ex anomalia media p haberetur, discreparet: hęc autem discrimen nonnunquam ultra 8 gradus exurgere posset, ideoque correctiones admodum notabiles requireret. Ut igitur nobis quam minimae correctiones inuestigandae relinquantur, expediet differentiam inter locum Lunae verum, et locum corporis quod secundum regulas Kepleri in ellipti circa Terram reuolueretur, ita tamen mobili, ut eius motus abscissam cum motu apogei Lunae per observationes cognito conueniret. Seu quod eodem redit, quaeramus primo ex anomalia Lunae media p secundum regulas Kepleri anomaliam eius veram quae sit $= r$, vnde si longitudo apogei fuerit $= w$, quantitas, $w + r$ nunquam multum ultra gradum a longitudine Lunae vera differet: vnde discrimen paulo facilius inueniri poterit, si quidem debita orbitae lunaris excentricitas in calculum inducatur. Hinc loco anomaliae Lunae mediae p eius anomaliam veram, quae scilicet mediae pro excentricitate rite assumpta contineatur, in aequationes nostras inferamus.

§. 38. Tabulae quidem astronomicae excentricitatem orbitae lunaris plerumque variabilem statuant; sed cum hic non de vera huius orbitae excentricitate quaestio sit, quam de excentricitate illius orbitae ellipticae mobilis, in qua corpus motum proximae motum Lunae referat; huius excentricitas media erit statuenda inter maximam ac minimam, quae vulgo orbitae lunari tribuuntur: vnde ista excentricitas media colligitur $= 0$, 05445. Ne autem huic conclusioni minimum fidamur

genera-

generatim hanc excentricitatem ponamus $= k$; atque anomalia vera per mediam ita determinabitur, ut sit

$$d p = \frac{(1-kk)^3}{(1-k \cos r)^2} d r, \text{ vel sit breuius gratia } \frac{1-kk}{1-k \cos r} = z,$$

ut sit $d p = \frac{z d r}{(1-kk)}$. Porro autem reliqua differentia

talia ita ad elementum $d r$ reuocabuntur, ut sit:

$$d s = \frac{r d r \sqrt{1-ee}}{(1-kk)} = d s, \text{ et } d s = \frac{r d r}{z \sqrt{1-kk}} \left(C - \frac{r d r \sqrt{1-ee}}{m s} \right) - \frac{r d r \sqrt{1-ee}}{m s \sqrt{1-kk}}.$$

§. 39. Si motus Lunae cum motu huius corporis, quod imaginamur, perfecte conueniret, tum vbi que foret $z = \frac{1-kk}{1-k \cos r}$ seu $z = 1$; quoniam autem hi

quo motus inter se non conueniunt, non erit $z = 1$, Ponamus ergo esse:

$$z = k'' = \frac{(1-kk)''}{1-k \cos r} \text{ seu } x = \frac{(1-kk)''}{1-k \cos r}$$

vbi primum obseruo, quantitatem $''$ valde parum a unitate recedere. Erit autem quantitas variabilis, quae alium terminum constantem praeter unitatem non inuoluet: nam si alium terminum constantem contineret, is in $''$ posset comprehendi, idque indicio esset distantiam mediam $''$ non recte esse assumptam. Habebit ergo $''$ huiusmodi formam $1 + Z$, vbi Z ex terminis non nisi variabilibus constabit. Praeterea autem animaduertit, hanc quantitatem Z nullum terminum huius formae $a \cos r$ complecti debere; quoniam hoc indicio esset excentricitatem k non recte esse assumptam, sed eam vel maiorem vel minorem accipi oportuisse.

E 2 §. 40. His

§. 40. His igitur notatis, quod quantitas n primo terminum constantem $= 1$ contineat, cum vero nullum terminum formae $\alpha \cos r$ involuat, statuerimus

$$x = t n \text{ seu } z = \frac{(1-kk)^n}{1-k \cos r}$$

postro brevitatis gratia $t = \frac{1-kk}{1-k \cos r}$. Atque cum supra elementum dp constans posuissimus, hac conditione exuenda erit $dz = dp \frac{dz}{dp}$, et $\frac{dz}{dp} = \frac{1}{dp} \frac{dz}{dt}$. Divisa ergo secunda aequatione per dp^2 , erit:

$$\text{II. } \frac{1}{dp} \frac{dz}{dp} = \frac{CC}{t^3 n^3} - \frac{2CS}{m^2 t^3 n^3} + \frac{SS}{n^2 t^3 n^3}$$

$$- \frac{m}{m^2 t n} (1 - \frac{3}{4} \text{tange}^2 + \frac{3}{4} \text{tange}^2 \cos 2(\Phi - \pi)) + \frac{m}{n} + \frac{t}{2 m n \omega^2} + \frac{3 t n \cos 2 \eta}{2 m n \omega^2} + \frac{3 v t t n}{8 m n \omega^4} (3 \cos \eta + 5 \cos 3 \eta)$$

III. $\frac{dx}{dt} = \frac{-t n d p}{C m - S} \sin(\Phi - \pi) \sin(\theta - \pi) \left(\frac{3 t n \cos \eta}{\omega^2} + \frac{3 v t t n}{4 \omega^4} (3 t \cos 3 \eta) \right)$ ubi nunc nullum differentiale assumtum est constans, sed iam pro habitu quoduis differentiale constans assumi poterit.

§. 41. Posito autem $x = t n$ et $dp = \frac{t dt}{V(1-kk)}$ existente $t = \frac{1-kk}{1-k \cos r}$ erit primo:

$$S = \sqrt{\frac{t dt}{V(1-kk)}} \left(\frac{3 t t n}{2 \omega^2} \sin 2 \eta + \frac{3 v^2 n^2}{8 \omega^4} (\sin \eta + 5 \sin 3 \eta) \right) \text{ seu}$$

$$S = \sqrt{\frac{t^2}{V(1-kk)}} \left(\frac{3 t^2 n^2}{2 \omega^2} \sin 2 \eta + \frac{3 v^2 t^2 n^2}{8 \omega^4} (\sin \eta + 5 \sin 3 \eta) \right) \text{ Hinc}$$

Hinc fiet $d\Phi = \frac{d r}{n n V(1-kk)} \left(C - \frac{S}{n} \right)$ atque

$$d \eta = \frac{d r}{n n V(1-kk)} \left(C - \frac{S}{n} \right) - \frac{t dt V(1-kk)}{m \omega V(1-kk)}$$

Porro autem ob $dx = t du + u dt$, erit $\frac{dx}{dp} = \frac{t du + u dt}{t dt} = \frac{du + u dt}{dt} V(1-kk)$ ac est $dt = - \frac{(1-kk) k dr \sin r}{(1-k \cos r)^2} = - \frac{k dt dr \sin r}{1-kk}$; sicque fiet

$$\frac{dx}{dp} = \frac{du V(1-kk)}{t dr} - \frac{k u \sin r}{V(1-kk)}; \text{ ac posito elemento } dr \text{ constans}$$

$$\text{erit } \frac{dx}{dp} = \frac{du V(1-kk)}{t dr} - \frac{k u \sin r}{V(1-kk)} \text{ hinc ob } \frac{dt}{dt} = - \frac{k dr \sin r}{1-kk} \text{ habebitur:}$$

$$\frac{dx}{dp} = \frac{du V(1-kk)}{t dr} - \frac{k u \cos r}{V(1-kk)}$$

§. 42. Hinc iam porro obtinemus pro secunda aequatione

$$\frac{1}{dp} \frac{dx}{dp} = \frac{(1-kk) du}{t^2 dr} - \frac{k u \cos r}{t}$$

qui valor substituitur in aequatione per $\frac{1-kk}{m}$ multiplicata oritur haec aequatio:

$$\text{II. } \frac{dx}{dr^2} - \frac{k u \cos r}{(1-kk) n^2} = \frac{2CS}{(1-kk) m n^2} + \frac{SS}{\omega^2 (1-kk)^2}$$

$$- \frac{m t}{m \omega (1-kk) n} (1 - \frac{3}{4} \text{tange}^2 + \frac{3}{4} \text{tange}^2 \cos 2(\Phi - \pi)) + \frac{m t^2}{m \omega (1-kk)} + \frac{t^2}{2 m (1-kk) \omega^2}$$

$$+ \frac{3 t^2 n \cos 2 \eta}{2 m (1-kk) \omega^2} + \frac{3 v t^2 n}{8 m \omega^4 (1-kk)} (3 \cos \eta + 5 \cos 3 \eta)$$

$$\text{III. } \frac{dx}{dr} = \frac{u dt}{(C n - S) V(1-kk)} \left(\frac{3 t^2 \cos \eta}{\omega^2} + \frac{3 v^2 t^2}{4 \omega^4} (3 + 5 \cos 3 \eta) \right) \text{ Quartam}$$

$$\text{E 3}$$

$$\text{Quartam}$$

$$\text{Quartam}$$

Quartam aequationem $d \tan \varphi = \frac{d \pi}{\tan(\varphi - \pi)}$, cum nullam mutationem subeat, superfluum foret continuo reperere.

§. 43. Conveniet autem quantitates constantes C et m , quartam valores nondum novimus, saltem vero proxime indagare, quae facilius deinceps ipsam aequationem resolutionem dirigere queamus. Perficuum autem est, si omnes quantitates a sinu solis pendentes ex calculo deleantur, tum utique fieri debere $u = 1$. Cum igitur primum S ab angulo η pendeat, terminos tam S quam η involuentes omitamus, ac pro ω quidem scribamus 1; quia tantum determinationem ad verum accedentem requirimus, quem in finem quoque inclinationem orbitae negligamus. Hinc aequatio secunda dabitur:

$$CC = \frac{mi}{1-kk} \frac{mi}{m(1-kk)} + \frac{u^3}{n^2(1-kk)} + \frac{t^4}{2m(1-kk)} \text{ siue}$$

$$CC = \frac{m^2}{m} \frac{u^3}{m} - k \cos \varphi - \frac{t^4}{2m}$$

Cum autem sit $\varphi = 1 + k \cos \varphi$ proxime, ob k valde parvum habebitur.

$$CC = \frac{m}{m} - \frac{t^4}{2m} + \frac{1}{2m}$$

$$+ \frac{m}{m} k \cos \varphi - \frac{3u^3}{m} \cos \varphi - \frac{2t^4}{m} \cos \varphi$$

Vnde perficuum esse oportere.

$$\frac{m}{m} = 1 + \frac{2+3u}{2m} \text{ et } CC = 1 + \frac{3+4u}{2m}$$

§. 44. His

cum

nitium
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res ex
Cum
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n scri-
acce-
nitio-
dabitur:

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e, ob k

§. 44. His

§. 44. His igitur constantium $\frac{m^2}{m}$ et CC valoribus proximis inveniendis ponamus esse reuera:

$$\frac{m}{m} = 1 + \frac{2+3u+\gamma}{m} \text{ et } CC = 1 + \frac{3+4u+\delta}{2m} = N$$

scribamus enim λ pro C, quia literis stansculis A, B, C, D etc. deinceps in operationibus sequentibus utemur: sicque fiet

$$S = \frac{1}{\sqrt{1-kk}} \int dr \left(\frac{3t^4 u^3}{2 \omega^3} \sin 2\eta + \frac{3v^2 u^3}{8 \omega^3} (\sin \eta + \sqrt{3} \eta) \right)$$

$$d\varphi = \frac{dr}{m \sqrt{1-kk}} \left(\lambda - \frac{S}{m} \right)$$

$$d\eta = \frac{dr}{m \sqrt{1-kk}} \left(\lambda - \frac{S}{m} \right) - \frac{t^4 dr \sqrt{1-ee}}{m \omega \sqrt{1-kk}}$$

$$\text{II. } \frac{(1-kk) ddu}{dr^2} = k u \cos \varphi + \frac{N \lambda - 2 \lambda S}{m u^3} + \frac{SS}{m^2} + \frac{u^3}{2m \omega^3}$$

$$= \frac{m^2}{m u^3} (1 - \frac{1}{2} \tan \varphi^2 + \frac{1}{2} \tan \varphi^2 \cos^2 \varphi (\varphi - \pi))$$

$$+ \frac{3t^4 u \cos^2 2\eta}{2m \omega^3} + \frac{3v^2 u^3 \sin \eta}{8m \omega^3} (3 \cos \eta + 5 \cos 3\eta)$$

$$\text{III. } dr = \frac{u dr \sin(\varphi - \pi) \sin(\theta - \pi)}{(N - mS) \sqrt{1-kk}} \left(\frac{3t^4}{\omega^3} \cos \eta + \frac{3v^2 u}{4 \omega^3} (3 + 5 \cos 2\eta) \right)$$

§. 45. Ponatur $\lambda = u \sqrt{1-kk}$, ut sit $u = 1 + \frac{3+4u+\delta}{2m}$

defectum enim in termino indefinito δ complecti licet, existente $m = m_0 + 2 + 3u + \gamma$; cum vero ponatur

$$S = (1-kk)^{\frac{1}{2}} \sqrt{R} dr, \text{ ut sit } R = \frac{dS}{dr \sqrt{1-kk}}; \text{ ac si pro } r \text{ et } e$$

$$r = \frac{1-kk}{1-k \cos \varphi} \text{ et } \omega = \frac{1-ee}{1-e \cos \varphi} \text{ habebimus:}$$

R =

$$R = \frac{3(1-kk)^2(1-e\cos r)^2}{2(1-e^2)^2(1-k\cos r)^2} \mu \sin 2\eta$$

$$+ \frac{3\psi(1-kk)^2(1-e\cos r)^2}{8(1-e^2)^2(1-k\cos r)^2} \mu^2 (\sin \eta + 5 \sin 3\eta)$$

$$\frac{dr}{dt} = \frac{1}{m} \sqrt{Rdr}; \text{ ubi } \frac{dr}{dt} = \frac{(1-kk)^{\frac{3}{2}}(1-e\cos r)^2}{m(1-e^2)^{\frac{3}{2}}(1-k\cos r)^2}$$

$$\frac{dt}{dr} = \frac{m}{\mu} \frac{\sqrt{Rdr}}{(1-kk)^{\frac{3}{2}}(1-e\cos r)^2}$$

§. 46. Aequatio autem secunda facta hac substitutione, si per $1 - kk$ dividatur, abit in sequentem:

$$II \frac{dhu}{dr} = \frac{ku \cos r}{1-k \cos r} + \frac{\mu}{m} \frac{2\psi \sqrt{Rdr}}{m\mu^2} + \frac{\mu(1-kk)^2}{m(1-k\cos r)^2}$$

$$+ \frac{m}{2m(1-e^2)^2(1-k\cos r)^2} \mu(1+3\cos 2\eta)$$

$$+ \frac{3\psi(1-kk)^2(1-e\cos r)^2}{8m(1-e^2)^2(1-k\cos r)^2} \mu^2 (3\cos \eta + 5\cos 3\eta)$$

$$III \frac{dhu}{dr} = \frac{d(\sin(\varphi-\pi)\sin(\theta-\pi))}{(1-kk)^2(1-e\cos r)^2} \frac{m \cos \eta}{(1-kk)^2(1-e\cos r)^2} + \frac{3\psi(1-kk)^2(1-e\cos r)^2}{4(1-e^2)^2(1-k\cos r)^2} \mu^2 (3+5\cos 2\eta)$$

Ac si e denotet inclinationem mediæ orbitæ Junaris, quantitas $1 - \frac{1}{2} \text{tang } \varphi^2 + \frac{1}{2} \text{tang } \theta^2 \cos 2(\varphi-\pi)$ in his duas partes dissecpi poterit:

$$(1 - \frac{1}{2} \text{tang } \varphi^2) + \frac{1}{2} (\text{tang } \theta^2 - \text{tang } \varphi^2 + \text{tang } \theta^2 \cos 2(\varphi-\pi))$$

quarum illa est constans, hæc vero proprie a nodo et inclinatione pender.

§. 47.

§. 47. Evoluamus autem producta illa ex r et ω orta, et quoniam excentricitates k et e sunt valde parvæ, sufficit ad eos vsque terminos tantum progredi, qui coefficientes habeant kk , ek et ee , eosque qui per altiores potestates sunt multiplicati omittere. Hinc erit:

$$I \frac{1-k\cos r}{1-k\cos r} = 1 + \frac{1}{2}kk + k\cos r + \frac{1}{2}k^2\cos 2r$$

$$\frac{k\cos r}{1-k\cos r} = \frac{1}{2}kk + k\cos r + \frac{1}{2}k^2\cos 2r$$

$$\frac{(1-kk)^2}{(1-k\cos r)^2} = 1 + 3k\cos r + \frac{1}{2}k^2\cos 2r$$

$$\frac{(1-kk)^{\frac{3}{2}}}{(1-k\cos r)^{\frac{3}{2}}} = 1 + 2k\cos r + \frac{1}{2}kk\cos 2r$$

$$\frac{(1-kk)^3}{(1-k\cos r)^3} = 1 + 2kk + 4k\cos r + 5kk\cos 2r$$

$$\frac{(1-kk)^4}{(1-k\cos r)^4} = 1 + 5k\cos r, \text{ quia hic terminus iam per } r \text{ est multiplicatus.}$$

§. 48. Porro vero pro terminis ex ω enatis est:

$$\frac{(1-e\cos r)^2}{(1-e)^2} = 1 + 2ee - 2e\cos r + \frac{1}{2}ee\cos 2r$$

$$\frac{(1-e\cos r)^3}{(1-e)^3} = 1 + \frac{3}{2}ee - 3e\cos r + \frac{3}{2}ee\cos 2r$$

$$\frac{(1-e\cos r)^4}{(1-e)^4} = 1 + 4e\cos r, \text{ quia hic factor tantum in minimis terminis occurrit.}$$

Hinc ergo colligimus:

$$\frac{(1-kk)^{\frac{3}{2}}(1-e\cos r)^2}{(1-e)^2(1-k\cos r)^2} = 1 + 2ee + 2k\cos r + \frac{1}{2}kk\cos 2r - 2e\cos r$$

$$- 2ek\cos(r+\psi) - 2ek\cos(r-\psi) + \frac{1}{2}ee\cos 2r$$

F (1-e^e)

§. 47.

$$\frac{(1-kk)^3(1-ee\cos^2s)^3}{(1-ee)^3(1-k\cos^2r)^4} = 1 + 2kk + \frac{2}{3}ee + 4kk\cos^2r + 5kk\cos^2r - 3e\cos^2r - 6ek\cos(r-s) - 6ek\cos(r+s) + \frac{2}{3}ee\cos^2s$$

$$\frac{(1-kk)^4(1-ee\cos^2s)^4}{(1-ee)^4(1-k\cos^2r)^5} = 1 + 5kk\cos^2r - 4e\cos^2s,$$

argue hinc fiet: $d\Phi = \frac{dr}{nu} (u - \frac{1}{m} \int R dr)$ atque

$$\frac{dr}{dr} = \frac{1+2ee}{n} + \frac{2k}{n} \cos^2r - \frac{2e}{n} \cos^2s - \frac{2ek}{n} (\cos^2r - s)$$

$$+ \frac{3kk}{2m} \cos^2r + \frac{ee}{2m} \cos^2s - \frac{2ek}{n} \cos^2(r+s)$$

$$\frac{dn}{dr} = \frac{n}{nu} \frac{\sqrt{Rdr}}{1-2ee} - \frac{2k}{n} \cos^2r + \frac{2e}{n} \cos^2s + \frac{2ek}{n} \cos^2(r-s)$$

$$- \frac{3kk}{2m} \cos^2r - \frac{ee}{2m} \cos^2s + \frac{2ek}{n} \cos^2(r+s)$$

§. 49. Introduce hinc nunc his valoribus evolutis in formulas nostras, hisque, qui per sinum cosinumque alterius anguli sunt multiplicati, pariter secundum simpliciter angulos explicatis, obtinebimus primum valorem ipsius R, qui erit:

$$R = \frac{1}{2} k k \sin(2\eta - 2r) + \frac{1}{2} k k \sin(2\eta - 2r) + \frac{1}{2} e e \sin(2\eta + s)$$

$$+ \frac{2}{3} e e \sin(2\eta - 2s) + \frac{2}{3} e e \sin(2\eta + 2s)$$

$$+ 3 e k \sin(2\eta - r + s) + 3 e k \sin(2\eta + r - s)$$

$$+ 3 e k \sin(2\eta - r - s) + 3 e k \sin(2\eta + r + s)$$

$$+ \frac{1}{2} k k \sin(\eta - r) + 2 e \sin(\eta - s)$$

$$+ \frac{1}{2} k k \sin(\eta + r) + 2 e \sin(\eta + s)$$

$$+ \frac{1}{2} k k \sin(3\eta - r) + 10 e \cos(3\eta - s)$$

$$+ \frac{1}{2} k k \sin(3\eta + r) + 10 e \cos(3\eta + s)$$

§. 50.

§. 50. Aequatio autem secunda principalis sequentem inducet formam:

$$\frac{dnu}{dr^2} = \frac{nu}{n^2} - \frac{2u\sqrt{Rdr}}{m n^2} + \frac{\sqrt{Rdr}^2}{n^2 u^2}$$

$$+ \frac{3m \text{ tang } \varrho^2}{4 n m n u} (1 - \cos^2(\vartheta - \pi)) (1 + k \cos^2r)$$

$$= \frac{m}{m n u} (1 + \frac{1}{2} k k + k \cos^2r + \frac{1}{2} k^2 \cos^2 2r) + \frac{u}{2m} (1 + 3k \cos^2r)$$

$$+ \frac{u}{n} (\frac{2}{3} k k + k \cos^2r + \frac{1}{3} k k \cos^2 2r)$$

$$+ \frac{u}{2m} (1 + 2kk + \frac{2}{3} ee + 4kk \cos^2r - 3e \cos^2s - 6ek \cos(r-s) + 5kk \cos^2r + \frac{2}{3} ee \cos^2s - 6ek \cos(r+s)$$

$$+ 3kk \cos^2r + \frac{2}{3} ee \cos^2s - 2ek \cos(r+s))$$

$$+ \frac{3u}{2m} (1 + 2kk + \frac{2}{3} ee) \cos^2 2\eta + 2ek \cos(2\eta - r) + 2ek \cos(2\eta + r)$$

$$+ \frac{3u}{2m} k k \cos(2\eta - 2r) + \frac{3u}{2m} k k \cos(2\eta + 2r)$$

$$+ \frac{3u}{2m} e e \cos(2\eta - 2s) + \frac{3u}{2m} e e \cos(2\eta + 2s)$$

$$+ \frac{3u}{2m} e k \cos(2\eta - r + s) + 3ek \cos(2\eta + r - s)$$

$$+ \frac{3u}{2m} e k \cos(2\eta - r - s) + 3ek \cos(2\eta + r + s)$$

$$+ \frac{3u m}{2m} [3 \cos^2\eta + 5 \cos^2 3\eta + \frac{2}{3} k k \cos^2(\eta - r) + \frac{2}{3} k k \cos^2(\eta + r)$$

$$+ 6 e \cos^2(\eta - s) + 6 e \cos^2(\eta + s) + \frac{2}{3} k k \cos^2(\eta - r) + \frac{2}{3} k k \cos^2(\eta + r)$$

$$+ 10 e \cos(3\eta - r) + 10 e \cos(3\eta + s)]$$

vbi terminos, qui adhuc ulteriori evolutione indigent, primo loco posui, et cum terminus tang ϱ^2 implicans iam sit valde parvus, in eius multiplicatore secundam ipsius k potestatem omisi: sin autem alicuius momenti videantur, loco I + $k \cos^2r$ scribi poterit I + $\frac{1}{2} k k$

§. 51. Pro longitudine vero nodi inveniendae aequatio sequens prohibet resoluenda:

F 2

dπ =

$$d\pi = \frac{3uvdr \sin(\Phi - \pi) \sin(\theta - \pi)}{kmm - \sqrt{Rdr}} \cos \eta (1 + 2kk + \frac{2}{3}ee + 4k \cos r$$

$$+ 5kk \cos 2r - 3e \cos s + \frac{2}{3}ee \cos 2s) \\ - \frac{3uv^2 dr \sin(\Phi - \pi) \sin(\theta - \pi)}{4(kmm - \sqrt{Rdr})} (3 + 5 \cos 2\eta) (1 + 5k \cos r)$$

At est $\sin(\Phi - \pi) \sin(\theta - \pi) = \frac{1}{2} \cos \eta - \frac{1}{2}(\Phi + \theta - 2\pi)$; unde $\sin(\Phi - \pi) \sin(\theta - \pi) \cos \eta = \frac{1}{4} + \frac{1}{4} \cos 2\eta - \frac{1}{4} \cos 2(\Phi - \pi) - \frac{1}{4} \cos 2(\theta - \pi)$ et $\sin(\Phi - \pi) \sin(\theta - \pi) \cos 2\eta = \frac{1}{4} \cos \eta + \frac{1}{4} \cos 3\eta$

$$- \frac{1}{4} \cos(3\Phi - \theta - 2\pi) - \frac{1}{4} \cos(3\theta - \Phi - 2\pi)$$

Tum vero ob \sqrt{Rdr} valde paruum prae kmm , erit satis exacte

$$\frac{1}{kmm - \sqrt{Rdr}} = \frac{1}{kmm} + \frac{\sqrt{Rdr}}{kmm^2} + \frac{(\sqrt{Rdr})^2}{k^3 m^3}$$

vbi quidem postremus terminus tuto omitti potest.

§. 52. Praeterea vero ponatur $n = 1 + \frac{v}{m}$, ut sit

$dkk = \frac{d\mu}{m}$, et reiectis terminis per n^4 divisis, qui iam

per exiguam quantitatem sunt multiplicati, erit

$$\frac{d\Phi}{dr} = n - \frac{2ku}{m} + \frac{3kv^2}{n^4} - \frac{\sqrt{Rdr}}{m} + \frac{2v\sqrt{Rdr}}{n^4}$$

$$\frac{d\eta}{dr} = k - \frac{1-2ee}{n} - \frac{2k}{n} \cos r + \frac{2e}{n} \cos s - \frac{3kk}{2n} \cos 2r - \frac{ee}{2n} \cos 2s$$

$$+ \frac{2ek}{n} \cos(r-s) + \frac{2ek}{n} \cos(r+s)$$

$$- \frac{2uv - \sqrt{Rdr}}{n^2} + \frac{3uv^2 + 2v\sqrt{Rdr}}{n^4} \quad \text{atque}$$

$$R = \frac{1}{2} (1 + 2kk + \frac{2}{3}ee) \sin 2\eta + 3k \sin(2\eta - r) - \frac{2}{3} e \sin(2\eta - s)$$

$$+ \frac{3v}{m} \sin 2\eta + \frac{3}{4} k \sin(2\eta + r) - \frac{2}{3} e \sin(2\eta + s)$$

$$+ \frac{3v^2}{m} \sin 2\eta + \frac{3}{4} k^2 \sin(2\eta - 2r) + \frac{2}{3} ee \sin(2\eta - 2s)$$

$$+ \frac{3v^2}{m^2} \sin 2\eta + \frac{3}{4} k^2 \sin(2\eta + 2r) + \frac{2}{3} ee \sin(2\eta + 2s)$$

$$+ \frac{3v^2}{m^2} \sin 2\eta - \frac{2}{3} ek \sin(2\eta - r + s) - \frac{2}{3} ek \sin(2\eta + r - s)$$

$$+ \frac{3v^2}{m^2} \sin 2\eta - \frac{2}{3} ek \sin(2\eta - r - s) - \frac{2}{3} ek \sin(2\eta + r + s)$$

$$+ \frac{6kv}{m} \sin(2\eta - r) + \frac{6kv}{m} \sin(2\eta + r)$$

$$- \frac{9ev}{2m} \sin(2\eta - s) - \frac{9ev}{2m} \sin(2\eta + s)$$

$$+ \frac{3}{2} v \sin \eta + \frac{3}{2} v k \sin(\eta - r) - \frac{3}{2} v e \sin(\eta - s)$$

$$+ \frac{3}{2} v k \sin(\eta + r) - \frac{3}{2} v e \sin(\eta + s)$$

$$+ \frac{3}{2} v^2 \sin 3\eta + \frac{3}{2} v^2 k \sin(\eta + r) - \frac{3}{2} v^2 e \sin(\eta + s)$$

$$+ \frac{3}{2} v^2 k \sin(3\eta + s) - \frac{3}{2} v^2 e \sin(3\eta + s)$$

§. 53. Ipsa vero aequatio secunda per hanc substitutionem, postquam per m fuerit multiplicata, in formam sequentem abit.

$$\text{II. } \frac{d\mu}{dr} = kmm - 3kuv + \frac{6uvv}{m} - 2k\sqrt{Rdr} \\ + \frac{6uv}{m} \sqrt{Rdr} + \frac{1}{m} (\sqrt{Rdr})^2$$

$$+ \frac{3m \tan \eta^2}{4} (1 - \cos 2(\Phi - \pi)) (1 + \frac{1}{2}kk + k \cos r + \frac{1}{2}kk \cos 2r)$$

$$- \frac{3uv \tan \eta^2}{2mm} (1 - \cos 2(\Phi - \pi)) (1 + k \cos r)$$

$$- \frac{3uvv}{n^4} (1 + k \cos r) - m (1 + \frac{1}{2}kk + k \cos r + \frac{1}{2}kk \cos 2r)$$

$$+ \frac{2mm}{n^2} (1 + \frac{1}{2}kk + k \cos r + \frac{1}{2}kk \cos 2r) + mm (\frac{1}{2}kk + k \cos r + \frac{1}{2}kk \cos 2r)$$

$$+ v (\frac{1}{2}kk + k \cos r + \frac{1}{2}kk \cos 2r) - m (1 + 3k \cos r)$$

$$+ \frac{1}{2} + kk + \frac{2}{3}ee - 2k \cos r - \frac{2}{3} e \cos s - 3ek \cos(r-s)$$

$$+ \frac{1}{2}kk \cos r + \frac{2}{3}ee \cos 2s - 3ek \cos(r+s)$$

$$+ \frac{v}{2m} (1 + 4k \cos r - 3e \cos s)$$

$$+ \frac{1}{2} (1 + 2kk + \frac{2}{3}ee) \cos 2\eta + 3k \cos(2\eta - r) - \frac{2}{3} e \cos(2\eta - s)$$

$$+ 3 \cos(2\eta + r) - \frac{2}{3} e \cos(2\eta + s) \\ \text{F} \\ 3$$

$$\begin{aligned}
& + \frac{1}{2} k k \operatorname{cof}(2\eta - 2r) + \frac{1}{2} e e \operatorname{cof}(2\eta - 2r) \\
& + \frac{1}{2} k k \operatorname{cof}(2\eta + 2r) + \frac{1}{2} e e \operatorname{cof}(2\eta + 2r) \\
& - \frac{1}{2} e k \operatorname{cof}(2\eta - r + s) - \frac{1}{2} e k \operatorname{cof}(2\eta + r - s) \\
& - \frac{1}{2} e k \operatorname{cof}(2\eta - r - s) - \frac{1}{2} e k \operatorname{cof}(2\eta + r + s) \\
& + \frac{3v}{2mn} \left[\operatorname{cof} 2\eta + 2k \operatorname{cof}(2\eta - r) + 2k \operatorname{cof}(2\eta + r) \right. \\
& \quad \left. - \frac{1}{2} e \operatorname{cof}(2\eta - s) - \frac{1}{2} e \operatorname{cof}(2\eta + s) \right] \\
& + \frac{1}{2} v \left[\begin{aligned} & + 3 \operatorname{cof} \eta + \frac{1}{2} k \operatorname{cof}(\eta - r) - 6 e \operatorname{cof}(\eta - s) \\ & + 5 \operatorname{cof} 3\eta + \frac{1}{2} k \operatorname{cof}(\eta + r) - 6 e \operatorname{cof}(\eta + s) \\ & + \frac{1}{2} k \operatorname{cof}(3\eta - r) - 10 e \operatorname{cof}(3\eta - s) \\ & + \frac{1}{2} k \operatorname{cof}(3\eta + r) - 10 e \operatorname{cof}(3\eta + s) \end{aligned} \right] \\
& + \frac{3v^2}{4mn} (3 \operatorname{cof} \eta + 5 \operatorname{cof} 3\eta)
\end{aligned}$$

§. 54. Cum autem sit $m = n + 2 + 3\mu + \gamma e k k =$
 $x + \frac{3 + 4\mu + \delta}{2n^2}$, si hi valores substituantur, plures
termini se mutuo destruent, aequatioque prodibit se-
quenti forma conciniori contenta: vbi quidem in ter-
minis per se minimis loco m scribi licebit n , et x loco
 $k k$ vel e .

II. ARQUATIO.

$$\begin{aligned}
\frac{d\theta}{dx} &= \frac{1}{2} \delta - \gamma + \frac{1}{2} e e - \gamma k \operatorname{cof} r + \frac{1}{2} k k \operatorname{cof} 2r \\
& - 2 \left(1 + \frac{3 + 4\mu + \delta}{4mn} \right) \sqrt{R} dr + \frac{1}{mn} (\sqrt{R} dr)^2 \\
& - v \left(1 - \frac{1}{2} k k - 3 k \operatorname{cof} r - \frac{1}{2} k k \operatorname{cof} 2r \right) \\
& + \frac{v^2}{mn} (3 - 3k \operatorname{cof} r) - \frac{1}{2} e \operatorname{cof} s + \frac{1}{2} e e \operatorname{cof} 2s - 3ek \operatorname{cof}(r - s) \\
& - 3ek \operatorname{cof}(r + s) + \frac{1}{2} (1 + 2kk + \frac{1}{2} e e) \operatorname{cof} 2\eta
\end{aligned}$$

$$\begin{aligned}
& + 3k \operatorname{cof}(2\eta - r) + \frac{1}{2} k k \operatorname{cof}(2\eta - 2r) - \frac{1}{2} e \operatorname{cof}(2\eta - s) \\
& + 3k \operatorname{cof}(2\eta + r) + \frac{1}{2} k k \operatorname{cof}(2\eta + 2r) - \frac{1}{2} e \operatorname{cof}(2\eta + s) \\
& + \frac{1}{2} e e \operatorname{cof}(2\eta - 2s) - \frac{1}{2} e k \operatorname{cof}(2\eta - r + s) - \frac{1}{2} e k \operatorname{cof}(2\eta - r - s) \\
& + \frac{1}{2} e e \operatorname{cof}(2\eta + 2s) - \frac{1}{2} e k \operatorname{cof}(2\eta + r + s) - \frac{1}{2} e k \operatorname{cof}(2\eta + r - s) \\
& + \frac{v}{mn} \left[\begin{aligned} & 2\gamma - \frac{1}{2} \delta + 6k \operatorname{cof} r + 2(3\mu + \gamma) k \operatorname{cof} r + 6\sqrt{R} dr \\ & - \frac{1}{2} e \operatorname{cof} s + \frac{1}{2} \operatorname{cof} 2\eta + 3k \operatorname{cof}(2\eta - r) + 3k \operatorname{cof}(2\eta + r) \\ & - \frac{1}{2} e \operatorname{cof}(2\eta - s) - \frac{1}{2} e \operatorname{cof}(2\eta + s) \end{aligned} \right] \\
& + \frac{1}{2} v \left[\begin{aligned} & 3 \operatorname{cof} \eta + \frac{1}{2} k \operatorname{cof}(\eta - r) - 6 e \operatorname{cof}(\eta - s) \\ & + 5 \operatorname{cof} 3\eta + \frac{1}{2} k \operatorname{cof}(\eta + r) - 6 e \operatorname{cof}(\eta + s) \\ & + \frac{1}{2} k \operatorname{cof}(3\eta - r) - 10 e \operatorname{cof}(3\eta - s) \\ & + \frac{1}{2} k \operatorname{cof}(3\eta + r) - 10 e \operatorname{cof}(3\eta + s) \end{aligned} \right] \\
& + \frac{3v^2}{4mn} (3 \operatorname{cof} \eta + 5 \operatorname{cof} 3\eta)
\end{aligned}$$

$$+ \frac{1}{2} (mn + 2 + 3\mu + \gamma) \frac{(1 - 2v)}{mn} \operatorname{tang}^2(r - \operatorname{cof} 2(\eta - r))$$

$$\left(1 + \frac{1}{2} k k + k \operatorname{cof} r + \frac{1}{2} k k \operatorname{cof} 2r \right)$$

§. 55. Pro loco nodi autem inveniendō prodibit
seguens aequatio.

$$\begin{aligned}
\frac{dx}{dr} &= \frac{1}{2} \left(1 + \frac{2kv + \sqrt{R} dr}{mn} \right) \left(1 + 2kk + \frac{1}{2} ee \right) \\
& + \frac{1}{2} + \frac{1}{2} \operatorname{cof} 2\eta - \frac{1}{2} \operatorname{cof} 2(\eta - r) - \frac{1}{2} \operatorname{cof} 2(\eta + r) \\
& + k \operatorname{cof} r + \frac{1}{2} k \operatorname{cof}(2\eta - r) - \frac{1}{2} k \operatorname{cof}(2\eta + r) \\
& - \frac{1}{2} e \operatorname{cof} s + \frac{1}{2} k \operatorname{cof}(2\eta + r) - \frac{1}{2} k \operatorname{cof}(2\eta - r) \\
& - \frac{1}{2} e \operatorname{cof}(2\eta - s) - \frac{1}{2} k \operatorname{cof}(2\theta - 2\pi - r) \\
& - \frac{1}{2} e \operatorname{cof}(2\eta + r) - \frac{1}{2} k \operatorname{cof}(2\theta - 2\pi + r) \\
& - \frac{3v}{4mn} \left[\frac{1}{2} k \operatorname{cof} \eta + \frac{1}{2} \operatorname{cof} 3\eta - \frac{1}{2} \operatorname{cof}(3\theta + \theta - 2\pi) \right. \\
& \quad \left. - \frac{1}{2} \operatorname{cof}(3\theta - \theta - 2\pi) \right]
\end{aligned}$$

At

At pro inclinatione orbis habeatur :

$$\frac{d}{dt} \text{tang} e = \frac{-3}{kMm} \left(1 + \frac{2k^2 + \frac{2}{3}e^2}{kMm} \sqrt{R} \frac{d^2}{dt^2} \right) (1 + 2kk + \frac{2}{3}e^2)$$

$$\begin{cases} \frac{3}{2} \sin 2(\phi - \pi) + \frac{3}{2} \sin 2(\theta - \pi) - \frac{3}{2} \sin 2\eta \\ - \frac{3}{2} k \sin(2\eta - r) + \frac{3}{2} k \sin(2\phi - 2\pi - r) \\ - \frac{3}{2} k \sin(2\eta + r) + \frac{3}{2} k \sin(2\phi - 2\pi + r) \\ + \frac{3}{2} e \sin(2\eta - s) + \frac{3}{2} k \sin(2\theta - 2\pi - r) \\ + \frac{3}{2} e \sin(2\eta + s) + \frac{3}{2} k \sin(2\theta - 2\pi + r) \end{cases}$$

$$- \frac{3^y}{4kMm} \left(- \frac{3}{2} \sin \eta - \frac{3}{2} \sin 3\eta + \frac{3}{2} \sin(\phi + \theta - 2\pi) \right)$$

$$+ \frac{3}{2} \sin(3\phi - \theta - 2\pi) + \frac{3}{2} \sin(3\theta - \phi - 2\pi)$$

Quomodo igitur his aequationibus ad motum Lunae cognoscendam vti conveniat, in sequentibus capitibus videamus.

CAPUT IV.

INVESTIGATIO INAEQUALITATIS LUNAE ABSOLUTAE, QUAE VARIATIO DICITUR.

§. 33.

Px his aequationibus perficitur in determinationem motus Lunae plurimorum angulorum vel sinus vel cosinus ingredi, qui anguli formantur per variationem combinationem sequentium 4 angulorum :

1. ex distantia Solis a Luna, quem angulum posuimus = η
 2. ex anomalia Lunae vera = r
 3. ex anomalia Solis vera = s
 4. ex distantia Lunae a nodo ascendente = $\phi - \pi$.
- Ne igitur a tanta angulorum multitudine obruamur, a casibus simplicioribus ordiamur : ac primo quidem in eas tantum motus inaequalitates inquiramus, quae a solo angulo η pendeant, neque idcirco excentricitatem vel Solis vel Lunae implicent, neque ab orbitae lunaris inclinatione ad eclipticam afficiantur.

§. 57. Has igitur inaequalitates, quae a solo fitu Solis respectu Lunae nascuntur, atque ab Astronomis sub nomine variationis comprehendendi solent, ex praecedentibus aequationibus elicimus, si tam excentricitatem Lunae k quam solis e pro nihilo habeamus, atque inclinationem orbitae lunaris ad eclipticam evanescentem faciamus, ita ut fit $k = 0$, $e = 0$ et tang $p = 0$. Sic enim obtinebimus eas inaequalitates Lunae, quae ab his elementis non pendent, ideoque tantum per angulum

tum η determinatur; quae cum vnicæ tabula comprehendendi queant, hæc tabula variationem Lunæ indicare dicitur. Interim tamen hic animadverti oportet, partem quandam exiguam variationis quoque ab excentricitate orbitæ Lunæ k pendere, quam partem deinceps superabimus, cum huius excentricitatis rationem summus habebimus.

§. 58. Reiectis ergo terminis k, e , et tang p continentibus, habebimus:

$$\begin{aligned} \frac{d\phi}{dr} &= \kappa - \frac{2\kappa v - \sqrt{Rdr}}{n} + \frac{3\kappa v^2 + 2v\sqrt{Rdr}}{n^2} \\ \frac{d\eta}{dr} &= \kappa - \frac{1 - 2\kappa v - \sqrt{Rdr}}{n} + \frac{3\kappa v^2 + 2v\sqrt{Rdr}}{n^2} \\ R &= \frac{3}{2} \sin 2\eta + \frac{3v}{n} \sin 2\eta + \frac{3}{2} v \sin \eta + \frac{3}{2} v^2 \sin 3\eta, \text{ ac denique} \\ \frac{d^2v}{dr^2} &= \frac{3}{2} \delta - \gamma - \frac{v}{n} \left(1 + \frac{3+4\mu+\delta}{4n} \right) \sqrt{Rdr} + \frac{1}{m} \left(\sqrt{Rd\delta} \right)^2 - v^2 + \frac{3v^2}{m} \\ &+ \frac{3}{2} \cos 2\eta + \frac{v}{n} (2\gamma - \frac{3}{2} \delta) + \frac{3v^2 \cos 2\eta}{2n} + \frac{6v^2}{n} \int R dr \\ &+ \frac{3}{2} \cos \eta + \frac{3}{2} v \cos 3\eta \end{aligned}$$

Hic autem notandum est esse $\kappa = \sqrt{1 + \frac{3+4\mu+\delta}{2n}}$;

quoniam vero valores litterarum μ et δ demum cum per contentum observationum, tum per indolem calculi definire instituitur, hic ex observationibus Peanrus valores ipsius κ ; cum enim sit $\kappa: 1 = d\phi: d\tau$, hoc est vt motus Lunæ medius ad motum anomalie, erit $\kappa = 1, 0085272$. Fieri quidem potest, vt hic valor aliquantulum a vero differat, sed errorem si quis latent infra detegamus, facillimeque emendabimus.

§. 59.

comprehendere indicare partem nutricitate eps super sumus

continen-

$$\begin{aligned} \text{denique} & \\ -v^2 + \frac{3v^2}{m} & \\ \int R dr & \end{aligned}$$

$\frac{\mu+\delta}{2n}$);
n cum
calculi
nus va-
: est vt
: $\kappa =$
: liquan-
: infra
§. 59.

§. 59. Cum igitur iam supra inuenimus esse $n = 13, 25586$ ac proinde $n^2 = 175, 71795$

erit $\frac{1}{n} = 0, 075438$, ideoque $\kappa - \frac{1}{n} = 0, 933089$

Hic autem numerus, qui iam quasi medium valorem rationis $\frac{d\eta}{dr}$ exprimit, in omnibus operationibus, quae sequuntur, frequentissime occurret, hincque breuitatis gratia ponamus

$$\kappa - \frac{1}{n} = a, \text{ vt sit } a + \frac{1}{n} = \sqrt{1 + \frac{3+4\mu+\delta}{2n}}$$

erique ergo $a = 0, 933089$, qui valor quam minime a vero discrepat, vt mox patebit. Quod autem verus ipsius a valor aliquantulum diuersus esse possit, inde primo patet, quod minutias, quae ex terminis $\frac{3\kappa v^2 + 2v\sqrt{Rdr}}{n^2}$

quantitati constanti accrescere potuissent, hic neglectimus; tum vero fieri potest, vt ratio media differentialium $d\eta$ ad dr alia sit atque quantiarum finitarum η et τ .

§. 60. Si has formulas atterne contemplerur, mox deprehendemus valorem integralis $\int R dr$ constare ex cosinibus angulorum $2\eta, \eta, 3\eta$, et 4η . Quamquam enim actiora quoque multiplica huius anguli ingrediuntur, tamen facile patet, coefficientes eorum continuo fieri minores, ita vt in quadruplo tuto subsistere possimus: similis autem erit ratio valoris ipsius v . Hinc ponamus:

$$\int R dr = A \cos 2\eta + B \cos 4\eta + a v \cos \eta + b v \cos 3\eta$$

argue hos valores ficticios in formulis nostris substitua-

mus:

§. 2

mus, ut inde valores istorum coefficientium assumto-
rum determinare possimus: quippe qui modus apiffi-
mus videtur ad cognitionem integralium perveniendi.
Quia autem est circiter $\nu = \frac{1}{282}$, patet terminos per ν
multiplicatos prae reliquis tam esse exiguos, ut eos qui
multo fuerint minores, sine haesitatione praetermittere
possimus.

§. 61. Per hos ergo valores assumtos consequemur:

$$\begin{aligned} \frac{d\phi}{dr} &= \kappa - \frac{(2\kappa A + 2\mathfrak{N})}{n} \operatorname{cof} 2\eta - \frac{(2\kappa B + 2\mathfrak{S})}{n} \operatorname{cof} 4\eta \\ &+ \frac{A(3\kappa A + 2\mathfrak{N})}{2n^2} \operatorname{cof} 2\eta + \frac{A(3\kappa A + 2\mathfrak{N})}{2n^2} \operatorname{cof} 4\eta \\ &- \frac{(2\kappa a + a)}{n} \nu \operatorname{cof} \eta - \frac{(2\kappa b + b)}{n} \nu \operatorname{cof} 3\eta \end{aligned}$$

arque ob $\kappa = \frac{1}{n} = a$ erit minimis terminis omissis,

quia hi in operatione multo magis diminuerentur:

$$\begin{aligned} \frac{d\eta}{dr} &= a - \frac{(2\kappa A + 2\mathfrak{N})}{n} \operatorname{cof} 2\eta - \frac{(2\kappa B + 2\mathfrak{S})}{n} \operatorname{cof} 4\eta \\ &- \frac{(2\kappa a + a)}{n} \nu \operatorname{cof} \eta - \frac{(2\kappa b + b)}{n} \nu \operatorname{cof} 3\eta \end{aligned}$$

His positis erit:

$$\begin{aligned} \frac{d(\operatorname{cof} 2\eta)}{dr} &= -\operatorname{fin} 2\eta \cdot \frac{2d\eta}{dr} = -2a \operatorname{fin} 2\eta - \frac{(2\kappa B + 2\mathfrak{S})}{n} \operatorname{fin} 2\eta + \frac{(2\kappa A + 2\mathfrak{N})}{n} \operatorname{fin} 4\eta \\ &+ \frac{(2\kappa a + a)}{n} \nu \operatorname{fin} \eta + \frac{(2\kappa b + a)}{n} \nu \operatorname{fin} 3\eta \\ &- \frac{(2\kappa b + b)}{n} \nu \operatorname{fin} \eta \end{aligned}$$

2.

$$\begin{aligned} \frac{d(\operatorname{cof} 4\eta)}{dr} &= -\operatorname{fin} 4\eta \cdot \frac{4d\eta}{dr} = -4a \operatorname{fin} 4\eta + \frac{2(2\kappa A + 2\mathfrak{N})}{n} \operatorname{fin} 2\eta \\ \frac{d(\operatorname{cof} \eta)}{dr} &= -\operatorname{fin} \eta \cdot \frac{d\eta}{dr} = -a \operatorname{fin} \eta \\ \frac{d(\operatorname{cof} 3\eta)}{dr} &= -\operatorname{fin} 3\eta \cdot \frac{3d\eta}{dr} = -3a \operatorname{fin} 3\eta \end{aligned}$$

§. 62. Quod si iam secundum has formulae quan-
titas integralis $\int R dr$ differentietur, obtinebitur:

$$\begin{aligned} R &= (-2a\mathfrak{N} - \frac{\mathfrak{N}(2\kappa B + 2\mathfrak{S})}{n} + \frac{2\mathfrak{S}(2\kappa A + 2\mathfrak{N})}{n}) \operatorname{fin} 2\eta \\ &+ \frac{\mathfrak{N}(2\kappa A + 2\mathfrak{N})}{n} - 4a\mathfrak{S}) \operatorname{fin} 4\eta \\ &+ \left(\frac{\mathfrak{N}(2\kappa a + a)}{n} + \frac{\mathfrak{N}(2\kappa b + b)}{n} - a\alpha \right) \nu \operatorname{fin} \eta \\ &+ \left(\frac{\mathfrak{N}(2\kappa a + a)}{n} - 3a\alpha b \right) \nu \operatorname{fin} 3\eta \end{aligned}$$

Cum iam sit per hypothesin

$$\begin{aligned} R &= \frac{3}{2} \operatorname{fin} 2\eta + \frac{3A}{2n} \operatorname{fin} 4\eta + \frac{3}{2} \nu \operatorname{fin} \eta + \frac{3}{2} \nu \operatorname{fin} 3\eta \\ &- \frac{3B}{2n} \dots + \frac{3a}{2n} \nu + \frac{3a}{2n} \nu \\ &- \frac{3b}{2n} \nu \end{aligned}$$

prodit terminis homogeneis comparandis:

$$\begin{aligned} 2a\mathfrak{N} &= -\frac{3}{2} - \frac{\mathfrak{N}(2\kappa B + 2\mathfrak{S}) + 2\mathfrak{S}(2\kappa A + 2\mathfrak{N})}{n} + \frac{3B}{2n} \\ 4a\mathfrak{S} &= -\frac{3A}{2n} + \frac{\mathfrak{N}(2\kappa A + 2\mathfrak{N})}{n} \\ a\alpha &= -\frac{3}{2} - \frac{3(a-b)}{2n} + \frac{\mathfrak{N}(2\kappa a + a) - \mathfrak{N}(2\kappa b + b)}{n} \\ 3a\alpha b &= -\frac{3a}{2n} + \frac{\mathfrak{N}(2\kappa a + a)}{n} \end{aligned}$$

G 3

§. 63.

2.

§. 63. Aequatio autem nostra differentio-differentials, si pro \sqrt{R} dx et v valores assumi substituantur, sequentem induet formam:

$$\begin{aligned} \frac{dxv}{dx} = & (\frac{3}{2}x - y) - 2x^2 \cos^2 y - 2x^2 B \cos^4 y - 2x^2 B \cos^6 y - 2x^2 B \cos^8 y \\ & + \frac{9x^2}{2mn} \qquad \qquad \qquad + \frac{9x^2}{2mn} \\ & - A \qquad \qquad \qquad - A \\ & + \frac{3AA}{2mn} \qquad \qquad \qquad + \frac{3AA}{2mn} \\ & + \frac{3}{2} \qquad \qquad \qquad + \frac{3}{2} \\ & + \frac{(4y-3\theta)}{2mn} A + \frac{(4y-3\theta)}{2mn} B \qquad + \frac{3^2 b}{4mn} v \qquad + \frac{3^2 a}{4mn} v \\ & + \frac{3A}{4mn} + \frac{3B}{4mn} \qquad \qquad \qquad + \frac{3A}{4mn} v \qquad + \frac{3B}{4mn} v \\ & + \frac{3A^2}{2mn} \qquad \qquad \qquad + \frac{3A^2}{2mn} v \qquad + \frac{3B^2}{2mn} v \end{aligned}$$

vbi quidem perfectum est, quinam termini respectu reliquorum tam sint parvi, vt sine errore deleri queant.

§. 64. Queramus ergo primum differentiale $\frac{dx}{dx}$

ac reperietur:

$$\begin{aligned} (-2Aa - \frac{A(2xB + 2S)}{mn} + \frac{2B(2xA + 2T)}{mz}) \sin 2y \\ (-4aB + \frac{A(2xA + 2T)}{mn}) \sin 4y \\ \frac{dx}{dx} = (-a + \frac{A(2xa + 0)}{mn} - \frac{A(2xb + 0)}{mz}) v \sin y \\ (-3ab + \frac{A(2xa + 0)}{mn}) v \sin 3y \end{aligned}$$

pona-

ponatur autem breuiatis ergo:

$$\frac{dx}{dx} = - A' \sin 2y - B' \sin 4y - a' v \sin y - b' v \sin 3y$$

vt fit:

$$\begin{aligned} A' = 2aA + \frac{A(2xB + 2S)}{mn} - \frac{2B(2xA + 2T)}{mz} \\ B' = 4aB - \frac{A(2xA + 2T)}{mn} \\ a' = a - \frac{A(2xa + 0)}{mn} + \frac{A(kb + b)}{mz} \\ b' = 3ab - \frac{A(2xa + 0)}{mn} \end{aligned}$$

§. 65. Hinc cum fit:

$$\begin{aligned} \frac{dx}{dx} = c \frac{2d}{2d} - \frac{2ac \frac{2d}{2d}}{2d} - \frac{(2kB + 2S)}{2d} c \frac{2d}{2d} - \frac{(2kA + 2T)}{2d} c \frac{2d}{2d} \\ \frac{dx}{dx} = \frac{2d}{2d} - \frac{2ac \frac{2d}{2d}}{2d} - \frac{(2kA + 2T)}{2d} v \cos^2 y - \frac{(2kb + b)}{2d} v \cos^4 y - \frac{(2ka + 0)}{2d} v \cos^6 y \\ \frac{dx}{dx} = \frac{2d}{2d} - \frac{2ac \frac{2d}{2d}}{2d} - \frac{2(2kA + 2T)}{2d} c \frac{2d}{2d} - \frac{2(2kB + 2S)}{2d} c \frac{2d}{2d} \\ \frac{dx}{dx} = \cos^2 y - \frac{2ac \frac{2d}{2d}}{2d} v \cos^2 y; \text{ et } \frac{dx}{dx} = \cos^2 y - \frac{3d}{2d} v \cos^2 y \\ \text{prodit} \\ + \frac{A'(2xA + 2T)}{mn} + \frac{2B'(2xB + 2S)}{mz} \\ (-2aA' + \frac{A'(2kB + 2S)}{mn} + \frac{2B'(2xA + 2T)}{mz}) \cos 2y \\ (-4aB' + \frac{A'(2xA + 2T)}{mn}) \cos 4y \\ (-a' + \frac{A'(2xa + 0)}{mn}) v \cos y \\ (-3ab' + \frac{A'(2xa + 0)}{mn}) v \cos 3y \end{aligned}$$

feu

Seu substitutus superioribus valoribus:

$$+ \frac{2Aa(2kA + 2\mathcal{N})}{m} + \frac{8aB(2kB + 2\mathcal{S})}{m}$$

$$(-4aaA + \frac{12aB(2kA + 2\mathcal{N})}{m}) \cos 2n$$

$$\frac{dku}{d\gamma^2} = (-16aaB + \frac{8aA(2kA + 2\mathcal{N})}{m}) \cos 4n$$

$$(-aaa + \frac{3aA(2ka + a)}{m} - \frac{aA(2kb + b)}{m}) \nu \cos n$$

$$(-9aab + \frac{5aA(2ka + a)}{m}) \nu \cos 3n$$

§ 66. Hi iam termini singularem illis, qui §. 63. sunt exhibit, aequales statuantur, atque sequentes prodibunt determinationes,

$$\frac{2\delta - \gamma + \frac{3AA + 6A\mathcal{N} + 2\mathcal{N}^2}{2m} + \frac{3A - 2aA(2kA + 2\mathcal{N})}{4m} + \frac{8aB(2kB + 2\mathcal{S})}{m} + \frac{3B}{4m} = -4aaA + \frac{12aB(2kA + 2\mathcal{N})}{m}$$

$$-A + \frac{3 - 2k\mathcal{N}}{2m} + \frac{(4\gamma - 3\delta)}{4m} A + \frac{3B}{4m} = -4aaA + \frac{12aB(2kA + 2\mathcal{N})}{m}$$

$$-B - 2k\mathcal{S} + \frac{3AA + 6A\mathcal{N} + 2\mathcal{N}^2}{2m} + \frac{3A}{4m} + \frac{(4\gamma - 3\delta)}{2m} B = -16aaB + \frac{8aA(2kA + 2\mathcal{N})}{m}$$

$$-a + \frac{3 - 2k\mathcal{N}}{4m} + \frac{3\delta + 3\delta}{4m} = -aa + \frac{3aA(2ka + a)}{m} - \frac{aA(2kb + b)}{m}$$

$$-\delta + \frac{3\delta - 2k\mathcal{N}}{4m} + \frac{3a}{4m} = -9aab + \frac{5aA(2ka + a)}{m}$$

Unde primum quaeri debent valores vero proximi, qui sunt:

$$\mathcal{N} = -\frac{3}{4a}; a = -\frac{3}{8a}; b = -\frac{5}{8a};$$

$$A = -\frac{\frac{3}{4} + 2k\mathcal{N}}{4aa - 1}; \mathcal{N} = \frac{\frac{3}{8} - 2k\mathcal{N}}{1 - aa}; b = -\frac{\frac{5}{8} + 2kb}{9aa - 1}$$

§. 67.

§. 67. Calculus ergo sequenti modo instituitur:

$$a = 0, 933089; la = 9, 969923$$

$$k = 1, 008527; lb = 0, 003687$$

$$\text{Iam est } l_{2k} = 0, 304717$$

$$\text{subtr. a } l_{8a} = 0, 873013$$

$$\left. \begin{aligned} l_3 &= 0, 477121 \\ l_5 &= 0, 698970 \end{aligned} \right\}$$

$$a = 0, 402; \text{ erit } l_{-a} = 9, 604108$$

$$b = 0, 635; l_{-b} = 9, 825957$$

$$\mathcal{N} = 0, 804; l_{-\mathcal{N}} = 9, 905138$$

$$\text{atque hinc conficietur: } A = -\frac{3, 121}{4aa - 1}; a = -\frac{1, 936}{1 - aa}; b = -\frac{3, 156}{9aa - 1}$$

$$\text{quorum ergo litterarum valores proximi sunt } A = -1, 2583; a = -14, 968; b = -0, 4613$$

$$\text{§. 68. Quaeramus hinc primum valores litterarum } \mathcal{S} \text{ et } B.$$

$$\mathcal{N} = -0, 804; l_{-\mathcal{N}} = 9, 905138$$

$$2kA + \mathcal{N} = -3, 341; \text{ unde colligitur } 4a\mathcal{S} = +\frac{4, 573}{m}$$

$$\text{hinc erit } l_{2k\mathcal{S}} = 0, 660201$$

$$\text{Deinde est } \mathcal{S} = +0, 00697; l_{\mathcal{S}} = 7, 843402$$

$$(16aa - 1)B = 2k\mathcal{S} - \frac{3A}{4m} - \frac{3AA - 6A\mathcal{N} - 2\mathcal{N}^2}{2m} + \frac{8aA(2kA + 2\mathcal{N})}{m}$$

$$\text{seu } B = +\frac{0, 16819}{16aa - 1}; \text{ unde reperitur } B = +0, 012792 \text{ et } l_B = 8, 106947$$

§. 69.

§. 69. His iam valoribus proxime veris inuentis
quaerantur exacti, ac primo quidem

$$2aA = -\frac{2}{3} + \frac{\frac{2}{3}B - \mathcal{N}(2kB + 28) + 2\mathcal{N}(2kA + \mathcal{N})}{m}$$

vide reperitur vt ante :

$$2A = -0,80378 \dots l - \mathcal{N} = 9,905138$$

$$aa = -\frac{2}{3} - \frac{\frac{2}{3}(a-b) + \mathcal{N}(2kA + a) - \mathcal{N}(2kb + b)}{m} = -0,65361$$

$$a = -0,70048 \dots l - a = 9,845396$$

$$3ab = -\frac{2}{3} - \frac{\frac{2}{3}a + \mathcal{N}(2kA + a)}{m} = -2,13900$$

$$b = -0,76413 \dots l - b = 9,883167$$

$$(4ka-1)A = -\frac{2}{3} + \frac{2k\mathcal{N} - \frac{2}{3}B + 12kB(2kA + \mathcal{N})}{m} = -9,12379$$

$$A = -1,25826 \dots l - A = 0,099771$$

$$(1-aa)a = \frac{2}{3} - 2kA + \frac{\frac{2}{3}(a+b) - 3aA(2kA + a) + aA(2kb + b)}{m} \text{ vel}$$

$$(1-a)a = \frac{3}{4m} + \frac{(6kaA)}{m} a = \frac{2}{3} - 2kA$$

$$+ \frac{\frac{2}{3}b - 3aAa + aA(2kb + b)}{m} = -2,53335$$

$$\text{hinc } a = +30,989 \text{ et } l - a = 1,491207$$

Vnde patet valorem ipsius a ante inuentum non satis
esse exactum, exactior ergo probabit ex hac formula

$$\left(\frac{a-b}{m}\right)a = -\frac{2}{3} - \frac{\frac{2}{3}(a-b) + \mathcal{N}(2kA - 2kb - b)}{m} = -0,93709$$

$$\text{hinc } a = -0,99939 \text{ et } l - a = 9,999735$$

vnde etiam exactius valor ipsius a reperitur, ex quo
denno

inuentis

18

,65361

16

0

17

,12379

1

b) vel

17

n satis

nula

93709

5

x quo

denno

denno valor ipsius a corrigetur, sique tandem satis ex-
acte obtinebitur

$$a = -1,2537 \dots l - a = 0,098200$$

$$a = +44,48 \dots l - a = 1,648165$$

$$b = -0,95003 \dots l - b = 9,977736$$

§. 70. Hinc iam accuratius quaeramus valorem

ipsius b

$$(9aa-1)b = -\frac{2}{3} + 2kA - \frac{\frac{2}{3}a + 5aA(2kA + a)}{m}$$

$$b = -1,0146 \dots l - b = 0,006314$$

vnde si denno precedentes valores corrigantur, fiet

$$a = -1,2530 \dots l - a = 0,101403$$

$$b = -0,9500 \dots l - b = 9,977736$$

$$a = +44,525 \dots l - a = 1,648604$$

$$b = -1,015 \dots l - b = 0,006400$$

$$2A = -0,80378 \dots l - \mathcal{N} = 9,905138$$

$$28 = +0,00697 \dots l - \mathcal{N} = 7,843402$$

$$A = -1,25826 \dots l - A = 0,099771$$

$$B = +0,01279 \dots l - B = 8,106947$$

His autem valoribus inuentis colligitur fore

$$\frac{2}{3}b - \gamma = +0,01742$$

Hic autem valor partem insuper accipit cum ab excentri-
citate virtusque orbitae, cum ab inclinatione oriundam,
quam deinceps determinabimus.

§. 71. Ex his ergo valoribus habebimus :

$$\sqrt{Rd} = -0,80378 \text{ col } 2^{\circ} + 0,00697 \text{ col } 4^{\circ}$$

$$9,905138 \quad 7,843402$$

$$-1,2630 \text{ v col } 1^{\circ} \quad -0,9500 \text{ v col } 3^{\circ}$$

$$0,101403 \quad 9,977736$$

H 2

$$v = 1,25826 \cos 2 \eta + 0,01279 \cos 4 \eta$$

$$0,099771 \quad 8,106947$$

$$+ 44,525 v \cos \eta \quad - 1,015 v \cos 3 \eta$$

$$1,648604 \quad 0,006400$$

hincque porro

$$\frac{d\Phi}{d\tau} = k + 0,019015 \cos 2 \eta - 0,0000762 \cos 4 \eta$$

$$8,279096 \quad 5,881955$$

$$+ 0,0001103 \quad - 0,50381 v \cos \eta + 0,017068 v \cos 3 \eta$$

$$9,702270 \quad 8,232184$$

at est $\frac{d\eta}{d\tau} = \frac{d\Phi}{d\tau} - \frac{1}{n}$, posuimusque $k - \frac{1}{n} = a$, exi-

stente $k = V \left(1 + \frac{3+4\mu+\delta^2}{2\mu^2} \right)$

§. 72. Ponatur breuitatis gratia

$$\frac{d\Phi}{d\tau} = \Omega + \wp \cos 2 \eta - \Omega \cos 4 \eta - \wp v \cos \eta + \Theta v \cos 3 \eta$$

erit $\frac{d\eta}{d\tau} = a + \wp \cos 2 \eta - \Omega \cos 4 \eta - \wp v \cos \eta + \Theta v \cos 3 \eta$

fitque ad integrandum:

$$\Phi = v \tau + \mu \sin 2 \eta - q \sin 4 \eta - r v \sin \eta + s v \sin 3 \eta$$

unde per differentiationem elicitur:

$$\frac{d\Phi}{d\tau} = 0 + 2\mu \cos 2 \eta - 4q \cos 4 \eta - a v \cos \eta + 3a\delta v \cos 3 \eta$$

$$\wp \mu - \Omega \mu \cos 2 \eta + \wp v \cos 4 \eta - \wp v v \cos \eta - \wp v v \cos 3 \eta$$

$$+ 2\Omega q - 2\wp q \cos 2 \eta \quad + 2\wp q v \cos 3 \eta$$

hinc ergo fit:

$$0 = \Omega - \wp \mu - 2\Omega q = k + 0,0001103 - \wp \mu - 2\Omega q$$

$$(2a - \Omega) \mu = \wp + 2\wp q; \quad 4a q = \Omega + \wp \mu;$$

$$a v = \wp - \wp \mu; \quad 3a\delta = \Theta + \wp v (\mu - 2q)$$

Ergo

Ergo $\mu = 0,010191 \dots$ $1\mu = 8,008208$
 $q = 0,000072 \dots$ $1q = 5,859381$
 $r = 0,53453 \dots$ $1r = 9,727977$
 $\delta = 0,00790 \dots$ $1\delta = 7,897466$
 $0 = k - 0,000080$

§. 73. Longitudo igitur lunae Φ quatenus pendet

a sola distantia lunae a sole erit

$$\Phi = (k - 0,000080) \tau + 0,010191 \sin 2 \eta - 0,53453 v \sin \eta$$

$$- 0,000072 \sin 4 \eta + 0,00790 v \sin 3 \eta$$

Simili modo cum distantia lunae a terra posita sit $= \frac{a(t-t_0)}{r-k \cos r}$, ob $\mu = 1 + \frac{v}{n}$, quatenus valor ipsius μ a sola phasi lunae penderet, erit

$$\mu = 1 - 0,00716 \cos 2 \eta + 0,00287 v \cos \eta$$

$$+ 0,00007 \cos 4 \eta - 0,00009 v \cos 3 \eta$$

Verum tamen hic valor litterae a ac praecipue ipsius a non admodum certus videtur, cum a terminis neglectis licet minimis insignem mutationem perpeti queat. Hic enim pro a non solum $k - \frac{1}{n}$ sed $k - \frac{1}{n} + 0,0001103$ accipi debuisse; quare cum valorem ipsius a propius cognoscimus, hanc determinationem repeti conueniet.

2 cos 4 η
 v cos 3 η
 +
 a, exi-
 5 v cos 3 η
 5 v cos 3 η
 5 v cos 3 η
 v sin 3 η
 5 v cos 3 η
 5 v cos 3 η
 1 v cos 3 η
 - 2 Ω q
 ;
 Ergo

CAPUT V.

INVESTIGATIO INAEQUALITATUM
LUNAE AB EIUS EXCENTRICITATE SIMPLICI
SOLUM PEDENTIVM.

§. 74.

Quemadmodum in praecedenti capite inaequalitas absoluta seu variatio duabus partibus confians est inventa, quarum posterior a littera ν seu a parallaxi solis pendeat, ac maiorem curam requirebat; ita etiam inaequalitates, quas hoc capite scribamur, partes continent ab eadem parallaxi solis pendentes; quarum indagatio quoque accuratorem cognitionem quorundam elementorum exigat. Hancobrem et praecedentis capitae et huius partes, quae litteram ν involvunt deinceps, cum reliquis inaequalitatibus, a parallaxi solis non pendentes determinaverimus, seorsim investigabimus, atque titulo inaequalitatum parallacticarum complectemur.

§. 75. In hoc ergo capite ac sequentibus, donec ad parallaxin solis perveniamus, terminos formularum nostrarum per ν multiplicatos tantisper remouebimus; et quoniam hoc loco tantum propositum est in motus lunae inaequalitates a sola excentricitate orbitae lunaris oras inquirere, eos terminos qui vel excentricitatem solis e vel inclinationem q continent, praetermittemus. Cum autem in formulis nostris duplicis generis terminos relinquantur, quorum alteri per k , alteri per h sunt affecti, inaequalitates ab excentricitate lunae k pendentes in

UM
CI

ualitas
ins est
a pa-
at; ita
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nceps,
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donec
llarum
inus;
motus
unaris
katem
emus.
rmini
ne af-
lentes
in

in duas partes distribui conueniet; quarum altera excentricitatem tantum simplicem k implicet, cui hoc capite destinatur, altera vero excentricitatis huius quadratae h afficiatur, de quo in sequenti capite agemus.

§. 76. Verum tam in huius generis inaequalitates, quam in sequentes, omnes inaequalitates absolutae in praecedenti capite eritae praecipue ingrediuntur; ex quo eas quoque in calculum introduci oportebit. Retinendae ergo erunt in calculo litterae \mathfrak{A} , \mathfrak{B} et A , B , quarum valores cum iam consent, calculus vehementer contrahetur: imprimis autem quia valores litterarum \mathfrak{B} et B per se sunt admodum parui, quatenus illi in valores sequentium terminorum insunt; effectum pro nihilo habendum praestabunt. Investigationem eritae nostram ita incipiemus, ut pro \sqrt{Rdr} et ν valores fictos assumamus, et quoniam \sqrt{Rdr} nullum terminum constantem, ν vero neque constantem neque terminum huius formae $a \cos r$ continere debet, ponamus:

$$\sqrt{Rdr} = \mathfrak{A} \cos 2\eta + \mathfrak{B} \cos 4\eta + \mathfrak{C} k \cos r$$

$$+ \mathfrak{D} k \cos (2\eta - r) + \mathfrak{E} k \cos (4\eta - r)$$

$$+ \mathfrak{G} k \cos (2\eta + r) + \mathfrak{H} k \cos (4\eta + r)$$

$$\nu = A \cos 2\eta + B \cos 4\eta$$

$$+ D k \cos (2\eta + r) + F k \cos (4\eta - r)$$

$$+ E k \cos (2\eta - r) + G k \cos (4\eta + r)$$

vbi quidem facile colligere liceat, coefficientes \mathfrak{D} , \mathfrak{F} et \mathfrak{G} fore minimos.

§. 77.

§. 77. Ex his autem valoribus assumtis obtinebimus ex (§. 52.) sequentes expressiones.

$$\begin{aligned} & k + \frac{A(3kA+2\mathfrak{M})}{2n^4} - \frac{(2kA+\mathfrak{M})}{n^2} \operatorname{cof} 2\eta \\ & (-\frac{2kB+\mathfrak{B})}{n^2} + \frac{A(3kA+2\mathfrak{M})}{2n^4} \operatorname{cof} 4\eta \\ & (-\frac{\mathfrak{C}}{n^2} + \frac{3kAD}{n^4} + \frac{A\mathfrak{D}+\mathfrak{M}D}{n^4}) k \operatorname{cof} r \\ & \frac{d\Phi}{dr} = \frac{(2kD+\mathfrak{D})}{n^2} k \operatorname{cof}(2\eta-r) - \frac{(2kE+\mathfrak{E})}{n^2} k \operatorname{cof}(2\eta+r) \\ & \quad - \frac{(2kF+\mathfrak{F})}{n^2} k \operatorname{cof}(4\eta-r) - \frac{(2kG+\mathfrak{G})}{n^2} k \operatorname{cof}(4\eta+r) \\ & \quad + \frac{(3kAD+A\mathfrak{D}+\mathfrak{M}D)}{n^4} k \operatorname{cof}(4\eta-r) \end{aligned}$$

Parebit enim ex valoribus qui inveniuntur, litteras D et \mathfrak{D} tantum prae reliquis fore notabiles, unde terminos ex combinatione reliquarum litterarum ortundos tuto omittere licet. Pro valore autem ipsius $\frac{d\eta}{dr}$ etiam hi termini ex combinatione orti omitri poterunt. Posito ergo $k + \frac{A(3kA+2\mathfrak{M})}{2n^4}$

— $\frac{1}{n}$ seu $k + \mathfrak{O}$, coarctes $-\frac{1}{n} = a$ erit:

$$\begin{aligned} \frac{d\eta}{dr} &= a - \frac{(2kA+\mathfrak{M})}{n^2} \operatorname{cof} 2\eta - \frac{2k}{n} \operatorname{cof} r \\ & - \frac{(2kD+\mathfrak{D})}{n^2} k \operatorname{cof}(2\eta-r) - \frac{(2kE+\mathfrak{E})}{n^2} k \operatorname{cof}(2\eta+r) \end{aligned}$$

Cum enim haec formula differentiationibus inficiendis inferuat, reliqui termini post primum cum aliis angulis combinantur, sicque tanto minores terminos producunt;

cunt, qui ex calculo sine errore expungi poterunt: atque ob hanc causam in expressione valoris $\frac{d\eta}{dr}$, statim terminos prae reliquis admodum parvos praetermittere visam est.

§. 78. Valorem autem ipsius R atque $\frac{d\eta}{dr}$ accuratissime exhiberi oportet, propterea quod his expressionibus totus calculus praecipue innititur, dum valor $\frac{d\eta}{dr}$ formulam tantum subsidiariam suppediat. Erit ergo

$$\begin{aligned} R &= \frac{3}{2} \operatorname{fn} 2\eta + \frac{3}{2n^2} \operatorname{fn} 4\eta + 3k \operatorname{fn}(2\eta-r) + 3k \operatorname{fn}(2\eta+r) \\ & + \frac{3A}{n^2} k \operatorname{fn}(4\eta-r) + \frac{3A}{n^2} k \operatorname{fn}(4\eta+r) \\ & + \frac{3D}{2n^2} k \operatorname{fn} r - \frac{3E}{2n^2} k \operatorname{fn} r \\ & + \frac{3D}{2n^2} k \operatorname{fn}(4\eta-r) + \frac{3E}{2n^2} k \operatorname{fn}(4\eta+r) \\ & - \frac{3A}{n^2} k \operatorname{fn} r + \frac{3A}{n^2} k \operatorname{fn} r \end{aligned}$$

vbi quidem terminos ab k non pendentes omittere possumus, quia illorum iam habuimus rationem, ita vt sic

$$\begin{aligned} R &= \dots + \frac{3(D-E)}{2n^2} k \operatorname{fn} r + 3k \operatorname{fn}(2\eta-r) + 3k \operatorname{fn}(2\eta+r) \\ & + \frac{3D}{2n^2} k \operatorname{fn}(4\eta-r) + \frac{3E}{2n^2} k \operatorname{fn}(4\eta+r) \\ & + \frac{3A}{n^2} k \operatorname{fn}(4\eta-r) + \frac{3A}{n^2} k \operatorname{fn}(4\eta+r) \end{aligned}$$

§. 79.

§. 79. Simili modo terminis a k non pendentibus omittendis habebitur :

$$\begin{aligned} \frac{d^2v}{dt^2} = & -\gamma k c f [3k c f (2\gamma - \gamma) + 3k c f (2\gamma + \gamma) - 2\gamma k c f (4\gamma - \gamma) - 2\gamma k c f (4\gamma + \gamma)] \\ & - \frac{2\gamma k \mathcal{C}}{2\gamma n} + \frac{2\gamma k \mathcal{D}}{2\gamma n} + \frac{2\gamma k \mathcal{E}}{2\gamma n} + \frac{2\gamma k \mathcal{F}}{2\gamma n} + \frac{2\gamma k \mathcal{G}}{2\gamma n} \\ & + \frac{2\gamma k \mathcal{H}}{2\gamma n} + \frac{2\gamma k \mathcal{I}}{2\gamma n} - D - E - F - G \\ & + \frac{3\gamma A D}{n} + \frac{3\gamma A E}{n} + \frac{3\gamma A F}{n} + \frac{3\gamma A G}{n} + \frac{3\gamma A H}{n} + \frac{3\gamma A I}{n} \\ & + \frac{3\gamma B D}{n} + \frac{3\gamma B E}{n} + \frac{3\gamma B F}{n} + \frac{3\gamma B G}{n} + \frac{3\gamma B H}{n} + \frac{3\gamma B I}{n} \\ & + \frac{3\gamma C D}{n} + \frac{3\gamma C E}{n} + \frac{3\gamma C F}{n} + \frac{3\gamma C G}{n} + \frac{3\gamma C H}{n} + \frac{3\gamma C I}{n} \\ & + \frac{3\gamma D D}{n} + \frac{3\gamma D E}{n} + \frac{3\gamma D F}{n} + \frac{3\gamma D G}{n} + \frac{3\gamma D H}{n} + \frac{3\gamma D I}{n} \\ & + \frac{3\gamma E D}{n} + \frac{3\gamma E E}{n} + \frac{3\gamma E F}{n} + \frac{3\gamma E G}{n} + \frac{3\gamma E H}{n} + \frac{3\gamma E I}{n} \\ & + \frac{3\gamma F D}{n} + \frac{3\gamma F E}{n} + \frac{3\gamma F F}{n} + \frac{3\gamma F G}{n} + \frac{3\gamma F H}{n} + \frac{3\gamma F I}{n} \\ & + \frac{3\gamma G D}{n} + \frac{3\gamma G E}{n} + \frac{3\gamma G F}{n} + \frac{3\gamma G G}{n} + \frac{3\gamma G H}{n} + \frac{3\gamma G I}{n} \\ & + \frac{3\gamma H D}{n} + \frac{3\gamma H E}{n} + \frac{3\gamma H F}{n} + \frac{3\gamma H G}{n} + \frac{3\gamma H H}{n} + \frac{3\gamma H I}{n} \\ & + \frac{3\gamma I D}{n} + \frac{3\gamma I E}{n} + \frac{3\gamma I F}{n} + \frac{3\gamma I G}{n} + \frac{3\gamma I H}{n} + \frac{3\gamma I I}{n} \end{aligned}$$

Hic scilicet plures terminos, qui nullius futuri essent momenti, omittimus, ne calculus nimium implicaretur: notandum autem est esse $\kappa = \gamma \left(1 + \frac{\gamma^2 + 4\mu + \delta}{2\gamma n} \right) = \frac{3 + 4\mu + \delta}{4\gamma n}$ proxime; vnde $\mu = (\kappa - 1) \gamma n = \frac{3 - \delta}{4}$ et $\frac{3 + 3\mu + \gamma}{4\gamma n} = 3(\kappa - 1) + \frac{3 - 3\delta + 4\gamma}{4\gamma n}$.

§. 80.

§. 80. Quæramus nunc quoque ex forma pro $R \frac{dv}{dt}$ fissa valorem ipsius R, atque exclusis terminis ab k non pendentibus reperiemus:

$$\begin{aligned} R = & \left(\frac{2\gamma}{n} - (2\alpha - 1) \mathcal{D} \right) k \sin(2\gamma - \gamma) \\ & + \frac{2\gamma}{n} - (2\alpha + 1) \mathcal{D} \quad k \sin(2\gamma + \gamma) \\ & + \frac{2\gamma}{n} - (2\alpha + 1) \mathcal{D} \quad k \sin(2\gamma + \gamma) \\ & + \frac{2\gamma}{n} - (2\alpha + 1) \mathcal{D} \quad k \sin(2\gamma + \gamma) \end{aligned}$$

argue infictura comparatione inuenietur:

$$\begin{aligned} \mathcal{D} = & \frac{2\gamma}{n} - 3 : (2\alpha + 1) \mathcal{D} = \frac{2\gamma}{n} - 3 ; \\ (4\alpha - 1) \mathcal{D} = & \frac{4\gamma}{n} + \frac{\gamma(2\alpha D + \mathcal{D}) + \mathcal{D}(2\alpha A + \mathcal{D}) - \frac{3}{2}(2A + D)}{\gamma(2\alpha D + \mathcal{D}) - \mathcal{D}(2\alpha A + \mathcal{D}) - \frac{3}{2}(D - E) - \gamma(2\alpha E + \mathcal{D})} \\ (4\alpha + 1) \mathcal{D} = & \frac{4\gamma}{n} + \frac{\gamma(2\alpha E + \mathcal{D}) - \frac{3}{2}(2A + E) + \mathcal{D}(2\alpha A + \mathcal{D})}{\gamma(2\alpha D + \mathcal{D}) - \mathcal{D}(2\alpha A + \mathcal{D}) - \frac{3}{2}(D - E) - \gamma(2\alpha E + \mathcal{D})} \end{aligned}$$

§. 81. Pro differentiali $\frac{dv}{dt}$ inueniendo, praeter terminos supra inventos habebimus:

$$\begin{aligned} \frac{dv}{dt} = & -A' \sin 2\gamma - B' \sin 4\gamma \\ & + \frac{A(2\alpha D + \mathcal{D}) - A(2\alpha E + \mathcal{D})}{n} + \frac{D(2\alpha A + \mathcal{D})}{n} + \frac{E(2\alpha A + \mathcal{D})}{n} \\ & + \frac{2A}{n} - (2\alpha - 1) \mathcal{D} \quad k \sin(2\gamma - \gamma) + \frac{2A}{n} - (2\alpha + 1) \mathcal{D} \quad k \sin(2\gamma + \gamma) \end{aligned}$$

§. 80.

I 2

$$C + \frac{A(2kD+\mathcal{D})}{n} + \frac{4B}{n} + \frac{D(2kA+\mathcal{D})}{n} - (4\alpha-1)F) k \sin(4\eta+r)$$

$$+ \frac{A(2kE+\mathcal{E})}{n} + \frac{4B}{n} + \frac{E(2kA+\mathcal{A})}{n} - (4\alpha+1)G) k \sin(4\eta+r)$$

Ponatur autem brevitatis gratia:

$$\frac{du}{dr} = - A' \sin 2\eta - B' \sin 4\eta - C' k \sin r - D' k \sin(2\eta-r)$$

$$- E' k \sin(2\eta+r) - F' k \sin(4\eta-r) - G' k \sin(4\eta+r)$$

vt fit:

$$A' = 2A\alpha + \frac{A(2kB+\mathcal{B})-2B(2kA+\mathcal{A})}{n}; B' = 4\alpha B - \frac{A(2kA+\mathcal{A})}{n}$$

$$C' = \frac{-A(2kD+\mathcal{D})+A(2kE+\mathcal{E})+(D-E)(2kA+\mathcal{A})}{n}$$

$$\text{five } C' = - \frac{A(\mathcal{D}-\mathcal{E})}{n} + \mathcal{D}(D-E)$$

$$D' = (2\alpha-1)D - \frac{2A}{n}; E' = (2\alpha+1)E - \frac{2A}{n}$$

$$F' = (4\alpha-1)F - \frac{4B}{n} - \frac{A(2kD+\mathcal{D})-D(2kA+\mathcal{A})}{n}$$

$$G' = (4\alpha+1)G - \frac{4B}{n} - \frac{A(2kE+\mathcal{E})-E(2kA+\mathcal{A})}{n}$$

§. 82. Hinc denno differentiando obtinebitur terminis tantum per k multiplicatis scribendis:

$$\frac{ddu}{dr^2} = (-C' + \frac{A'(2kD+\mathcal{D})}{n} + \frac{A'(2kE+\mathcal{E})}{n} + \frac{D'(2kA+\mathcal{A})}{n} + \frac{E'(2kA+\mathcal{A})}{n}) k \cos r$$

$$+ \frac{2A'}{n} - (2\alpha-1)D') k \cos(2\eta-r)$$

$$+ \frac{2A'}{n} - (2\alpha+1)E') k \cos(2\eta+r)$$

$$+ \frac{4B'}{n} + \frac{A'(2kD+\mathcal{D})}{n} + \frac{D'(2kA+\mathcal{A})}{n} - (4\alpha-1)F') k \cos(4\eta-r)$$

$$+ \frac{4B'}{n} + \frac{A'(2kE+\mathcal{E})}{n} + \frac{E'(2kA+\mathcal{A})}{n} - (4\alpha+1)G') k \cos(4\eta+r)$$

vnde comparatione infirma oritur:

$$\frac{3AA+3A(D+E)+2A(\mathcal{D}+\mathcal{E})+2\mathcal{D}(2D+E)+\mathcal{E}(\mathcal{D}+\mathcal{E})}{A(2kD+\mathcal{D})-A'(2kE+\mathcal{E})-(D'+E')(2kA+\mathcal{A})}$$

$$(2\alpha-1)^2 D - \frac{2(2\alpha-1)}{n} A - \frac{2A'}{n} + 3-2k\mathcal{D} - D$$

$$+ \frac{3}{n} A + \frac{\frac{3}{n}\mathcal{E} + (2\eta-\frac{3}{2}\delta)D}{n} + (3+3\mu+r)A$$

$$(2\alpha+1)^2 E - \frac{2(2\alpha+1)}{n} A - \frac{2A'}{n} + 3-2k\mathcal{E} - E$$

$$+ \frac{3}{n} A + \frac{\frac{3}{n}\mathcal{D} + (2\eta+\frac{3}{2}\delta)E}{n} + (3+3\mu+r)A$$

$$(4\alpha-1)^2 F - \frac{4(4\alpha-1)}{n} B - \frac{(4\alpha-1)A(2kD+\mathcal{D})-(4\alpha-1)D(2kA+\mathcal{A})}{n}$$

$$- \frac{4B'}{n} - \frac{A'(2kD+\mathcal{D})-D'(2kA+\mathcal{A})}{n} - 2k\mathcal{F} - F$$

$$+ \frac{3}{n} B + \frac{\frac{3}{n}\mathcal{D} + 3AD - 2AA + 3AD + 3\mathcal{D}D}{n}$$

$$(4\alpha+1)^2 G - \frac{4(4\alpha+1)}{n} B - \frac{(4\alpha+1)A(2kE+\mathcal{E})-(4\alpha+1)E(2kA+\mathcal{A})}{n}$$

$$- \frac{4B'}{n} - \frac{A'(2kE+\mathcal{E})-E'(2kA+\mathcal{A})}{n} - 2k\mathcal{G} - G$$

$$+ \frac{3}{n} B + \frac{\frac{3}{n}\mathcal{E} + 3AB - 2AA + 3AB + 3\mathcal{E}E}{n}$$

§. 83. Incipiamus a coefficientibus D, E, et D, E; et quia E est quantitas admodum exigua, erit:

$$(2a-1) D = -3 + \frac{2\delta}{n}; \quad (2a+1) E = -3 + \frac{2\delta}{n}$$

$$\left((2a-1)^2 - 1 + \frac{2\gamma - \frac{1}{2}\delta}{m} \right) D = -3 - \frac{1}{2}A + 2\kappa D$$

$$+ 2 \frac{(2a-1)}{n} A + \frac{2A'}{n} (3\kappa - 3 + \frac{3-3\delta+4\gamma}{4m}) A$$

$$\left((2a+1)^2 - 1 + \frac{2\gamma - \frac{1}{2}\delta}{m} \right) E = -3 - \frac{1}{2}A + 2\kappa E$$

$$+ 2 \frac{(2a+1)}{n} A + \frac{2A'}{n} (3\kappa - 3 + \frac{3-3\delta+4\gamma}{4m}) A$$

unde reperitur:

$$D = -3, 6035 \quad ; \quad 1-D = 0, 556724$$

ac porro

$$(-0,24973 + \frac{(2\gamma - \frac{1}{2}\delta)}{m}) D = -1,40048 - 7,4315$$

$$(+7,1497 + \frac{(2\gamma - \frac{1}{2}\delta)}{m}) E = -1,40048 - 2,7403$$

Quoniam autem valores ipsius $\frac{2\gamma - \frac{1}{2}\delta}{m}$ non-

dum nobis hunc terminum, cum certo sit valde parvus, relictimus. Postmodum vero cum istum terminum cognoverimus, facile erit correctionem inde oriundam, si opus fuerit, videlicet, indicere.

$$D = +35, 368 \quad ; \quad 1-D = 1, 548588$$

$$E = -9, 5739 \quad ; \quad 1-E = 9, 758848$$

Porro autem litterae S et U ita elicientur, vt fit:

$$(4a-1) S = 0, 000529 + 0, 01028 + 0, 02071 + 0, 02638$$

$$S = 0, 1907 \quad ; \quad 1-S = 9, 280416$$

$$U = 0, 0122 \quad ; \quad 1-U = 8, 087607$$

Praeterea autem colligimus fore

$$E = 0, 67465 \quad ; \quad 1-E = 9, 829072$$

unde erit proxime $\frac{3\delta}{2m} = 0, 00154$, ex quo accuratius concluditur fore

$$D = +35, 3724 \quad ; \quad 1-D = 1, 548664$$

$$E = -9, 5741 \quad ; \quad 1-E = 9, 758988$$

§. 85. Reliquae aequationes nobis praebunt

$$6, 4655 F + 3, 67820 = 0$$

$$21, 3946 G - 0, 29574 = 0$$

unde obtinebitur

$$F = -0, 56890 \quad ; \quad 1-F = 9, 755033$$

$$G = +0, 01382 \quad ; \quad 1-G = 8, 140620$$

ac denique $\gamma = 1, 40673$.

Supra autem iam invenimus $\frac{1}{2}\delta - \gamma = 0, 01742$, unde ambas istas quantitates γ et δ , quas initio ad veros valores confusantium litterarum m et n determinandos assumimus, nunc cognitas habemus, erit enim:

$$\delta = 2, 84830, \quad \text{et} \quad 2\gamma - \frac{1}{2}\delta = -1, 45899$$

ac propterea particulae illius $\frac{2\gamma - \frac{1}{2}\delta}{m}$ haecenus neglectae valor erit $\frac{2\gamma - \frac{1}{2}\delta}{m} = -0, 00832$, cuius ope iam litterae D et E accuratius definiti poterunt.

$$D = +35, 368 \quad ; \quad 1-D = 1, 548588$$

$$E = -9, 5739 \quad ; \quad 1-E = 9, 758848$$

§. 86. Hinc autem potissima valor ipsius D mutationem patitur, fiet enim re vera

$$D = 34, 24520 \dots \quad / D = 1, 534600$$

$$7, 20665 \quad E = -4, 14578 \quad \text{feu}$$

et quoniam D parte sua tricesima dimiuitur, in eadem fere ratione diminuentur valores litterarum G et Y, ita vt exadius fit:

$$G = -0, 65217 \dots \quad / G = 9, 814361$$

$$Y = +1, 35984 \dots \quad / Y = 0, 133490$$

$$Z = +2, 75336 \dots \quad / Z = 0, 439863$$

$$\text{et } \frac{2Y-Z}{m} = -0, 00804$$

Deinceps autem operæ erit pretium in hos valores ad huc diligentius inquirere.

§. 87. Cum igitur fixerimus sequentes valores:

$$R dr = \mathcal{A} \text{ cof } 2r + \mathcal{B} \text{ cof } 4r + \mathcal{C} k \text{ cof } r$$

$$+ \mathcal{D} k \text{ cof } (2r - r) + \mathcal{E} k \text{ cof } (4r - r)$$

$$+ \mathcal{F} k \text{ cof } (2r + r) + \mathcal{G} k \text{ cof } (4r + r)$$

$$= \mathcal{A} \text{ cof } 2r + \mathcal{B} \text{ cof } 4r$$

$$+ \mathcal{D} k \text{ cof } (2r - r) + \mathcal{E} k \text{ cof } (4r - r)$$

$$+ \mathcal{F} k \text{ cof } (2r + r) + \mathcal{G} k \text{ cof } (4r + r)$$

horum coefficientium valores sunt

$$\mathcal{A} = -0, 80378 \quad \mathcal{B} = -1, 25826$$

$$\mathcal{C} = +0, 00697 \quad \mathcal{D} = -0, 01279$$

$$\mathcal{E} = -0, 65217$$

$$\mathcal{F} = -3, 60350 \quad \mathcal{G} = +34, 24520$$

$$\mathcal{H} = -1, 08900 \quad \mathcal{I} = -0, 57527$$

$$\mathcal{J} = -0, 19070 \quad \mathcal{K} = -0, 56890$$

$$\mathcal{L} = +0, 01220 \quad \mathcal{M} = +0, 01382$$

vide

vide pro distantia lunæ a terra $x = \frac{(1-k)as}{1-k \text{ cof } r}$ fit

$$u = 1 - 0, 007161 \text{ cof } 2r + 0, 000073 \text{ cof } 4r$$

$$+ 0, 194888 k \text{ cof } (2r - r) - 0, 003274 k \text{ cof } (2r + r)$$

$$- 0, 003238 k \text{ cof } (4r - r) + 0, 000078 k \text{ cof } (4r + r)$$

§. 88. His valoribus in §. 77. substitutis obtinebimus:

$$\frac{d\phi}{dr} = \frac{+0, 0001103 - 0, 000076 \text{ cof } 4r}{m} + 0, 012278 k \text{ cof } (2r + r)$$

$$- 0, 38410 k \text{ cof } (2r - r) - 0, 000229 k \text{ cof } (4r + r)$$

$$+ 0, 002647 k \text{ cof } (4r - r)$$

ad cuius integrale inueniendum ponamus:

$$\phi = Or + \mathcal{M}' \text{ fin } 2r + \mathcal{N}' \text{ fin } 4r + \mathcal{O}' k \text{ fin } r$$

$$+ \mathcal{P}' k \text{ cof } (2r - r) + \mathcal{Q}' k \text{ cof } (2r + r)$$

$$+ \mathcal{R}' k \text{ cof } (4r - r) + \mathcal{S}' k \text{ cof } (4r + r)$$

critique differentiendo et terminis iam cognitis omitendis.

$$\frac{d\phi}{dr} = \frac{\mathcal{M}'(2kD + \mathcal{O})}{m} + \frac{\mathcal{N}'(2kE + \mathcal{Q})}{m} + \frac{\mathcal{O}'(2kA + \mathcal{P})}{m} + \frac{\mathcal{P}'k \text{ cof}}{m}$$

$$\left(- \frac{2\mathcal{M}'}{m} + (2a - 1) \mathcal{O}' \right) k \text{ cof } (2r - r)$$

$$\left(- \frac{2\mathcal{N}'}{m} + (2a + 1) \mathcal{Q}' \right) k \text{ cof } (2r + r)$$

$$\left(- \frac{4\mathcal{R}'}{m} + \frac{\mathcal{M}'(2kD + \mathcal{O})}{m} + \frac{\mathcal{O}'(2kA + \mathcal{P})}{m} \right) + (4a - 1) \mathcal{S}' k \text{ cof } (4r - r)$$

$$\left(- \frac{4\mathcal{S}'}{m} + \frac{\mathcal{M}'(2kE + \mathcal{Q})}{m} + \frac{\mathcal{Q}'(2kA + \mathcal{P})}{m} \right) + (4a + 1) \mathcal{R}' k \text{ cof } (4r + r)$$

Pro terminis autem iam inuenitis est

$$O = k - 0, 000080; \mathcal{M}' = 0, 010191; \mathcal{N}' = -0, 000072$$

$$/\mathcal{R}' = 8, 008208; / \mathcal{S}' = -5, 859381$$

§. 89.

§. 89. Comparatione iam instituta fiet:

$$\begin{aligned}
(2k-1)D &= -0,38410 + \frac{2S'}{n}; (2k+1)S' = +0,01278 + \frac{2S'}{n} \\
(4k-1)S' &= +0,002647 + \frac{4S'}{n} + \frac{S'(2kD+D)+D'(2kA+S')}{n} \\
(4k+1)S' &= -0,000229 + \frac{4S'}{n} + \frac{S'(2kE+S')+S'(2kA+S')}{n} \\
S' &= -0,001555 + \frac{S'(2kD+D)+D'(2kA+S')}{n} \\
&+ \frac{S'(2kE+S')+S'(2kA+S')}{n}
\end{aligned}$$

unde colligitur fore

$$\begin{aligned}
S' &= +0,01083 \\
D' &= -0,44167 \dots \dots \dots 1-D' = 9,645092 \\
S' &= +0,00499 \dots \dots \dots 1/S' = 7,698640 \\
S' &= +0,00545 \dots \dots \dots 1/S' = 7,737733 \\
S' &= -0,00010 \dots \dots \dots 1-S' = 6,002537
\end{aligned}$$

ita vt fit

$$\begin{aligned}
\Phi &= (k-0,000080r) + 0,010191 \sin 2q + 0,01083 k \sin r \\
&\quad - 0,000072 \sin 4q \\
&\quad - 0,44167 k \sin (2q-r) + 0,00499 k \sin (2q+r) \\
&\quad + 0,00546 k \sin (4q-r) - 0,00010 k \sin (4q+r) \\
\end{aligned}$$

unde ex comparatione motus medi ad modum anomalie erit $k = 1,008607$, et $a = 0,933279$, qui valores iam propius ad veritatem accedunt, quam haecenus viderunt.

CAPUT.

78 + $\frac{2S'}{n}$
 $\frac{2kA+S'}{n}$
 $\frac{2kA+S'}{n}$
 $\frac{2kA+S'}{n}$
 $\frac{A+S'}{n}$
 $\frac{A+S'}{n}$

92
40
33
37
83 k sin r
(2q+r)
(4q+r)
m ano-
9, qui
am ha-

APUT.

CAPUT VI.

INVESTIGATIO INAEQUALITATUM LUNAE A QUADRATO EXCENTRICITATIS IPSIUS ORTARUM.

§. 90.

Pervenimus nunc ad alteram partem inaequalitatum in motu Lunae, quae ab eius excentricitate & pendens, eiusque quadratum involvunt, ita vt hic notentur eos terminos sumus contemplaturi, qui per quadratum excentricitatis lunae k & sunt multiplicati. Hic autem tam in valorem ipsius \sqrt{Rdr} , quam ipsius φ terminorum formae $kk \cos 2q$ et $kk \cos 4q$ ingredientur, qui postquam fuerint inveniunt, terminis huius generis iam ante inuentis adici debent; praeterea vero vtriusque etiam termini formae $kk \cos 2r$ accedent. Hinc ponamus:

$$\begin{aligned}
\sqrt{Rdr} &= S' \cos 2q + a kk \cos 2q + S'S \cos 4q + b kk \cos 4q \\
&+ S' k \cos r + D' k \cos (2q-r) + S' k \cos (2q+r) \\
&+ S' k \cos (4q-r) + S' k \cos (4q+r) \\
&+ S' kk \cos 2r + S' kk \cos (2q-2r) + S' kk \cos (2q+2r) \\
&+ S' kk \cos (4q-2r) + S' kk \cos (4q+2r) \\
\varphi &= A \cos 2q + a kk \cos 2q + B \cos 4q + b kk \cos 4q \\
&+ D' k \cos (2q-r) + E' k \cos (2q+r) \\
&+ F' k \cos (4q-r) + G' k \cos (4q+r) \\
&+ H' kk \cos 2r + J' kk \cos (2q-2r) + K' kk \cos (2q+2r) \\
&+ L' kk \cos (4q-2r) + M' kk \cos (4q+2r)
\end{aligned}$$

K 2

§. 91.

§. 91. Nunc ad terminos, quibus ante valorem ipsius $\frac{d\phi}{dx}$ exprimi invenimus, insuper sequentes per k multiplicandi accedent:

$$\begin{aligned} \frac{d\phi}{dx} = & \dots + \frac{D(3kD+2\mathcal{D})}{2m^4} k^2 + \left(\frac{(2kA+q)}{ms} + \frac{\mathcal{D}}{n^4} \right) k^2 \operatorname{col} 2\eta \\ & \left(\frac{(2kb+b)}{ms} + \frac{D(3kE+2\mathcal{E})}{2m^4} + \frac{E(3kD+2\mathcal{D})}{2m^4} \right) k^2 \operatorname{col} 4\eta \\ & \left[\frac{(2kH+\mathcal{H})}{ms} + \frac{D(3kF+2\mathcal{F})}{2m^4} + \frac{F(3kD+2\mathcal{D})}{2m^4} \right] k^2 \operatorname{col} 2\eta \\ & \quad + \frac{A(3kJ+2\mathcal{J})}{2m^4} + \frac{J(3kA+2\mathcal{A})}{2m^4} \left] k^2 \operatorname{col} 2\eta \right. \\ & \left(\frac{(2kJ+\mathcal{J})}{ms} + \frac{A(3kH+2\mathcal{H})}{2m^4} + \frac{H(3kA+2\mathcal{A})}{n^4} + \frac{\mathcal{D}}{n^4} \right) k^2 \operatorname{col} (2\eta-2\tau) \\ & \left(\frac{(2kK+\mathcal{K})}{ms} + \frac{A(3kH+2\mathcal{H})}{2m^4} + \frac{H(3kA+2\mathcal{A})}{2m^4} \right) k^2 \operatorname{col} (4\eta+2\tau) \\ & \left(\frac{(2kL+\mathcal{L})}{ms} + \frac{A(3kJ+2\mathcal{J})}{2m^4} + \frac{J(3kA+2\mathcal{A})}{2m^4} + \frac{D(3kD+2\mathcal{D})}{2m^4} \right) k^2 \operatorname{col} (4\eta-2\tau) \\ & - \frac{(2kM+\mathcal{M})}{ms} k^2 \operatorname{col} (4\eta+2\tau) \end{aligned}$$

vbi quidem terminos, quos minimos fore facile est praevidere, omittimus.

§. 92. Terminus autem confusus $\frac{D(3kD+2\mathcal{D})}{2m^4} k$ reperitur = $q, 000175$, vnde posito $x + q, 000285 = \frac{1}{x} = a$, quoniam valorem ipsius $\frac{d\eta}{dx}$ non opus est tam exacte nosse, sumamus:

$$\frac{d\eta}{dx}$$

valorem per k

$k^2 \operatorname{col} 2\eta$

$k^2 \operatorname{col} 4\eta$

$k^2 \operatorname{col} 2\eta$

$\operatorname{col} (2\eta-2\tau)$

$\operatorname{col} (4\eta+2\tau)$

$\operatorname{col} (4\eta-2\tau)$

clie est

$\frac{2\mathcal{D}}{m^4} k$

000285

us est

$$\frac{d\eta}{dx}$$

$$\begin{aligned} \frac{d\eta}{dx} = & a - \frac{(2kA+\mathcal{A})}{ms} \operatorname{col} 2\eta - \left(\frac{2k}{n^2} + \frac{\mathcal{D}}{ms} \right) \operatorname{col} \tau \\ & - \frac{(2kD+\mathcal{D})}{ms} k \operatorname{col} (2\eta-\tau) - \left(\frac{3kk}{2m} + \frac{(2kH+\mathcal{H})}{ms} \right) \operatorname{col} 2\tau \\ & - \frac{(2kJ+\mathcal{J})}{ms} k^2 \operatorname{col} (2\eta-2\tau) \end{aligned}$$

Deinde vero praeter terminos iam tractatos habebitur:

$$\begin{aligned} R = & \dots + 3k^2 \sin 2\eta + \frac{3D}{ms} k^2 \sin 4\eta + \frac{3(2D+J)}{2ms} k^2 \sin 2\tau \\ & + (k^2 k^2 + 3(H-L)) \sin (2\eta-2\tau) + (k^2 k^2 + \frac{3H}{2ms}) \sin (2\eta+2\tau) \\ & + \frac{3(2D+J)}{2ms} k^2 \sin (4\eta-2\tau) \end{aligned}$$

aque simili modo:

$$\begin{aligned} \frac{dd\eta}{dx^2} = & \frac{1}{2} \delta - \gamma + \frac{3kA + \frac{1}{2} \mathcal{D} \mathcal{D} + 3\mathcal{D} \mathcal{D} + 3\mathcal{D} \mathcal{D} + 3Aa + 3\mathcal{B}k + 3Aa}{ms} k \\ & + (3 + \frac{1}{2} (A+D+E) - a - 2ka) k k \operatorname{col} 2\eta \\ & + (\frac{1}{2} (B+F+G) - b - 2kb) k k \operatorname{col} 4\eta \\ & + (\frac{1}{2} - 2k\mathcal{D} - H + \frac{3\mathcal{G} + 3\mathcal{J}}{ms} + 3A\mathcal{G} + 3AJ) k k \operatorname{col} 2\tau \\ & + (\frac{1}{2} - 2k\mathcal{E} - J + \frac{1}{2} A + \frac{1}{2} D) k k \operatorname{col} (2\eta-2\tau) \\ & + (\frac{1}{2} - 2k\mathcal{F} - K + \frac{1}{2} A + \frac{1}{2} E) k^2 \operatorname{col} (2\eta+2\tau) \\ & + (-2k\mathcal{L} - L + \frac{1}{2} B + \frac{1}{2} F) k k \operatorname{col} (4\eta-2\tau) \\ & + (-2k\mathcal{M} - M + \frac{1}{2} B + \frac{1}{2} G) k^2 \operatorname{col} (4\eta+2\tau) \\ & + \frac{3\mathcal{G} + 3\mathcal{J} \mathcal{G} + 3AJ + \frac{1}{2} \mathcal{D} \mathcal{D} + 3\mathcal{D} \mathcal{D} + 3\mathcal{D} \mathcal{D}}{ms} k k \operatorname{col} (4\eta-2\tau) \end{aligned}$$

§. 93. Eliciamus nunc quoque valorem ipsius R per differentiationem ex formula $\sqrt{R} dx$, ac terminis apte dispositis habebimus

$$K \ 3$$

$$R =$$

R =

$Kk \text{ fin } 24$ -2 a a $+ \frac{2b(2kA+9)}{2M}$ $+ \frac{D(2x+9)}{2M}$ $+ \frac{E(2x+9)}{2M}$ $+ \frac{2F(2xD+9)}{2M}$	$Kk \text{ fin } 44$ $+ \frac{a(2kA+9)}{2M}$ -4 a b $+ \frac{E(2xD+9)}{2M}$ $+ \frac{2F(2x+9)}{2M}$ $+ \frac{2G(2x+9)}{2M}$	$Kk \text{ fin } 24$ $+ \frac{2H(2kJ+9)}{2M}$ -2 f $+ \frac{E(2xD+9)}{2M}$ $+ \frac{2F(2kA+9)}{2M}$ $+ \frac{3G(2kA+9)}{2M}$	$K^2 \text{ fin } (24-2x)$ $+ \frac{3H}{2M}$ $+ \frac{2I(2kH+9)}{2M}$ $+ \frac{D(2x+9)}{2M}$ $+ \frac{2E(2kA+9)}{2M}$
--	--	---	---

$Kk \text{ fin } (24+2x)$ $+ \frac{3H}{2M}$ $+ \frac{2I(2kH+9)}{2M}$ $+ \frac{2J(2kJ+9)}{2M}$ $+ \frac{E(2x+9)}{2M}$ $+ \frac{2F(2xD+9)}{2M}$ $+ \frac{2G(2kA+9)}{2M}$ $+ \frac{2H(2kA+9)}{2M}$	$Kk \text{ fin } (44-2x)$ $+ \frac{2I(2kJ+9)}{2M}$ $+ \frac{3J(2kJ+9)}{2M}$ $+ \frac{2K(2kH+9)}{2M}$ $+ \frac{D(2xD+9)}{2M}$ $+ \frac{2E(2x+9)}{2M}$ $+ \frac{3F(2kA+9)}{2M}$ $+ \frac{2G(2kA+9)}{2M}$ $+ \frac{2H(2kA+9)}{2M}$	$Kk \text{ fin } (44+2x)$ $+ \frac{3J(2kJ+9)}{2M}$ $+ \frac{2K(2kH+9)}{2M}$ $+ \frac{2L(2x+9)}{2M}$ $+ \frac{3M(2kA+9)}{2M}$ $+ \frac{2N(2kA+9)}{2M}$
--	---	--

vnde

$(24-2x)$ $(H+9)$ $+ \frac{I+9}{2M}$ $+ \frac{D(2x+9)}{2M}$ $+ \frac{2E(2kA+9)}{2M}$
--

vnde orientur sequentes determinaciones :

$$3 = -2aa + \frac{2b(2kA+9)}{2M} + \frac{D(2x+9)}{2M} + \frac{2E(2xD+9)}{2M}$$

$$\frac{3D}{2M} = -4ab + \frac{a(2kA+9)}{2M} + \frac{E(2xD+9)}{2M} + 2 \frac{F(2x+9)}{2M}$$

$$\frac{3(2D+J)}{2M} = -2f + \frac{2H(2kJ+9)}{2M} + \frac{D(2xD+9)}{2M} - \frac{3G(2kA+9)}{2M}$$

$$\frac{I}{2M} + \frac{3(H-I)}{2M} = -2(a-1)G + \frac{3H}{2M} + \frac{2I(2kH+9)}{2M}$$

$$\frac{I}{2M} + \frac{3H}{2M} = 2(a+1)S + \frac{3H}{2M} + \frac{2I(2kH+9)}{2M}$$

$$+ \frac{2J(2kJ+9)}{2M} + \frac{2K(2kD+9)}{2M} + \frac{D(2x+9)}{2M} + \frac{2N(2kA+9)}{2M}$$

$$+ \frac{3(2D+J)}{2M} = -2(2x-1)E + \frac{3J(2kJ+9)}{2M} + \frac{2K(2kH+9)}{2M}$$

$$+ \frac{2L(2x+9)}{2M} + \frac{2M(2kA+9)}{2M} + \frac{2N(2kA+9)}{2M}$$

$$0 = -2(2x+1)M + \frac{3J(2kJ+9)}{2M} + \frac{2K(2kH+9)}{2M} + \frac{2L(2x+9)}{2M} + \frac{2M(2kA+9)}{2M}$$

§. 94. Deinde simili modo si ponatur :

$$\frac{A'}{A} = -A' \text{ fin } 24 - A'' \text{ fin } 24 - B' \text{ fin } 44 - B'' \text{ fin } 44$$

$$- C' \text{ fin } 4 - D' \text{ fin } (24-x) - E' \text{ fin } (44-x)$$

$$- F' \text{ fin } (24+x) - G' \text{ fin } (24+x)$$

$$- H' \text{ fin } 2x - I' \text{ fin } (24-2x) - L' \text{ fin } (44-2x)$$

$$- K' \text{ fin } (24+2x) - M' \text{ fin } (44+2x)$$

vnde

erit

erit praeter valores §. 81. datos:

$$\begin{aligned}
 d' &= \frac{2k(2kA+2) - (D+E)(2\alpha+2) - 2F(2\alpha D+2)}{2k} \\
 h' &= \frac{4ab - \frac{2(2kA+2)}{2k} - E(2\alpha D+2)}{2k} \\
 &\quad - \frac{2(F+G)(2\alpha+2) - D(2kE+2)}{2k} \\
 h' &= 2H - \frac{A(2kJ+2) - E(2\alpha D+2)}{2k} \\
 &\quad + \frac{(J-K)(2kA+2) + D(2kE+2)}{2k} \\
 j' &= \frac{2(\alpha-1)j - \frac{3A}{2k} - \frac{A(2kH+2) - D(2\alpha+2) - 2L(2kA+2)}{2k}}{2k} \\
 k' &= \frac{2(\alpha+1)k - \frac{3A}{2k} - \frac{A(2kH+2) - 2B(2kJ+2) - 2G(2\alpha D+2)}{2k}}{2k} \\
 &\quad - \frac{E(2\alpha+2) - 2M(2kA+2)}{2k} \\
 l' &= \frac{2(2\alpha-1)l - \frac{3B}{2k} - \frac{A(2kJ+2) - 2B(2kH+2) - D(2\alpha D+2)}{2k}}{2k} \\
 &\quad - \frac{2F(2\alpha+2) - J(2kA+2)}{2k} \\
 m' &= \frac{2(2\alpha+1)m - \frac{3B}{2k} - \frac{2B(2kH+2) - G(2\alpha+2) - K(2kA+2)}{2k}}{2k}
 \end{aligned}$$

vbi quidem plures terminos, quos admodum paruos fore praevidimus, omittimus.

§. 95.

§. 95. Hinc autem denno differentiando obtinemus

$$\text{valorem ipsius } \frac{d'dv}{d'p^2} =$$

$k k$	$k k \text{ cof } 2 \eta$	$k k \text{ cof } 4 \eta$	$k k \text{ cof } 2 \rho$
$\frac{d'(2kA+2)}{2k}$	$2 \alpha d'$	$\frac{d'(2kA+2)}{2k}$	$\frac{A'(2kJ+2)}{2k}$
$\frac{D'(2kD+2)}{2k}$	$\frac{2B'(2kA+2)}{2k}$	$4 \alpha b'$	$\frac{E'(2kD+2)}{2k}$
	$\frac{D'(2\alpha+2)}{2k}$	$\frac{E'(2\alpha D+2)}{2k}$	$2 H'$
	$\frac{E'(2\alpha+2)}{2k}$	$2 F'(2\alpha+2)$	$\frac{J'(2kA+2)}{2k}$
	$\frac{2F'(2\alpha D+2)}{2k}$	$2 G'(2\alpha+2)$	$\frac{K'(2kA+2)}{2k}$
$k k \text{ cof } (2\eta-2\rho)$	$k k \text{ cof } (2\eta+2\rho)$	$k k \text{ cof } (4\eta-2\rho)$	$k k \text{ cof } (4\eta+2\rho)$
$+\frac{3A'}{2k}$	$+\frac{3A'}{2k}$	$+\frac{A'(2kJ+2)}{2k}$	$+\frac{3B'}{2k}$
$+\frac{A'(2kH+2)}{2k}$	$+\frac{A'(2kH+2)}{2k}$	$+\frac{3B'}{2k}$	$+\frac{2B'(2kH+2)}{2k}$
$\frac{D'(2\alpha+2)}{2k}$	$\frac{2G'(2\alpha D+2)}{2k}$	$\frac{D'(2\alpha D+2)}{2k}$	$\frac{2G'(2\alpha+2)}{2k}$
$-\frac{2(\alpha-1)j'}{2k}$	$-\frac{2(\alpha+1)k'}{2k}$	$\frac{2F'(2\alpha+2)}{2k}$	$-\frac{2(2\alpha+1)m'}{2k}$
$\frac{2L'(2kA+2)}{2k}$	$\frac{2M'(2kA+2)}{2k}$	$-\frac{2(2\alpha-1)l'}{2k}$	$\frac{J'(2kA+2)}{2k}$
			$\frac{K'(2kA+2)}{2k}$

vnde

$$\begin{aligned}
 &D+2) \\
 &+ 2) \\
 &E+2) \\
 &+ 2) \\
 &3+2) \\
 &A+2) \\
 &D+2) \\
 &A+2) \\
 &A+2) \\
 &A+2) \\
 &partuos
 \end{aligned}$$

§. 95.

unde tandem nascitur has determinationes:

$$\begin{aligned}
 & \frac{1}{2} \delta - \gamma + \frac{3A + \frac{1}{2}D + 3D + \frac{1}{2}DD + 3AA + 3\mathcal{A} + 3AA}{\# \#} \\
 & = \frac{d'(2KA + \mathcal{A})}{\# \#} + \frac{D'(2KD + \mathcal{D})}{\# \#} \\
 & 3 + \frac{1}{2}(A + D + E) - d - 2KA = -2ad' + \frac{2B'(2KA + \mathcal{A})}{\# \#} \\
 & + \frac{(D + E)(2n + \mathcal{D}) + 2F'(2KD + \mathcal{D})}{\# \#} \\
 & \frac{1}{2}(B + F + G) - \delta - 2K\delta = -4aB' + \frac{d'(2KA + \mathcal{A})}{\# \#} \\
 & + \frac{E'(2KD + \mathcal{D}) + 2(F' + G')(2n + \mathcal{D})}{\# \#} \\
 & \frac{1}{2} - 2K\delta - H + \frac{3\mathcal{G} + 3\mathcal{H}J + 3A\mathcal{G} + 3AJ}{\# \#} = -2H' + \frac{A'(2KJ + \mathcal{G})}{\# \#} \\
 & + \frac{E'(2KD + \mathcal{D}) + (J' + K')(2KA + \mathcal{A})}{\# \#} \\
 & \frac{1}{2} - 2K\mathcal{G} - J + \frac{1}{2}A + \frac{1}{2}D = -2(a-1)J' + \frac{3A'}{2\#} + \frac{A'(2KH + \mathcal{G})}{\# \#} \\
 & + \frac{D'(2n + \mathcal{D}) + 2L'(2KA + \mathcal{A})}{\# \#} \\
 & \frac{1}{2} - 2K\mathcal{K} - K + \frac{1}{2}A + \frac{1}{2}E = -2(a+1)K' + \frac{3A'}{2\#} + \frac{A'(2KH + \mathcal{G})}{\# \#} \\
 & + \frac{2G'(2KD + \mathcal{D}) + 2M'(2aA + \mathcal{A})}{\# \#} \\
 & - 2K\mathcal{L} - L + \frac{1}{2}B + \frac{1}{2}F + \frac{3\mathcal{H}J + 3AJ + 3A\mathcal{H} + 3AD + 3D\mathcal{H} + 3DD}{\# \#} \\
 & = -2(a-1)L' + \frac{3B'}{\#} + \frac{A'(2KJ + \mathcal{G}) + 2B'(2KH + \mathcal{G})}{\# \#} \\
 & + \frac{D'(2KD + \mathcal{D}) + 2E'(2n + \mathcal{D}) + J'(2KA + \mathcal{A})}{\# \#}
 \end{aligned}$$

$$\begin{aligned}
 & \frac{1}{2} \delta - \gamma + \frac{3A + \frac{1}{2}D + 3D + \frac{1}{2}DD + 3AA + 3\mathcal{A} + 3AA}{\# \#} \\
 & = \frac{d'(2KA + \mathcal{A})}{\# \#} + \frac{D'(2KD + \mathcal{D})}{\# \#} \\
 & 3 + \frac{1}{2}(A + D + E) - d - 2KA = -2ad' + \frac{2B'(2KA + \mathcal{A})}{\# \#} \\
 & + \frac{(D + E)(2n + \mathcal{D}) + 2F'(2KD + \mathcal{D})}{\# \#} \\
 & \frac{1}{2}(B + F + G) - \delta - 2K\delta = -4aB' + \frac{d'(2KA + \mathcal{A})}{\# \#} \\
 & + \frac{E'(2KD + \mathcal{D}) + 2(F' + G')(2n + \mathcal{D})}{\# \#} \\
 & \frac{1}{2} - 2K\delta - H + \frac{3\mathcal{G} + 3\mathcal{H}J + 3A\mathcal{G} + 3AJ}{\# \#} = -2H' + \frac{A'(2KJ + \mathcal{G})}{\# \#} \\
 & + \frac{E'(2KD + \mathcal{D}) + (J' + K')(2KA + \mathcal{A})}{\# \#} \\
 & \frac{1}{2} - 2K\mathcal{G} - J + \frac{1}{2}A + \frac{1}{2}D = -2(a-1)J' + \frac{3A'}{2\#} + \frac{A'(2KH + \mathcal{G})}{\# \#} \\
 & + \frac{D'(2n + \mathcal{D}) + 2L'(2KA + \mathcal{A})}{\# \#} \\
 & \frac{1}{2} - 2K\mathcal{K} - K + \frac{1}{2}A + \frac{1}{2}E = -2(a+1)K' + \frac{3A'}{2\#} + \frac{A'(2KH + \mathcal{G})}{\# \#} \\
 & + \frac{2G'(2KD + \mathcal{D}) + 2M'(2aA + \mathcal{A})}{\# \#} \\
 & - 2K\mathcal{L} - L + \frac{1}{2}B + \frac{1}{2}F + \frac{3\mathcal{H}J + 3AJ + 3A\mathcal{H} + 3AD + 3D\mathcal{H} + 3DD}{\# \#} \\
 & = -2(a-1)L' + \frac{3B'}{\#} + \frac{A'(2KJ + \mathcal{G}) + 2B'(2KH + \mathcal{G})}{\# \#} \\
 & + \frac{D'(2KD + \mathcal{D}) + 2E'(2n + \mathcal{D}) + J'(2KA + \mathcal{A})}{\# \#}
 \end{aligned}$$

$$\begin{aligned}
 & -2K\mathcal{M} - M + \frac{1}{2}B + \frac{1}{2}G = -2(a+1)M' + \frac{3B'}{\#} + \frac{2B'(2KH + \mathcal{G})}{\# \#} \\
 & + \frac{2G'(2n + \mathcal{D}) + K'(2KA + \mathcal{A})}{\# \#}
 \end{aligned}$$

§. 96. Primum autem valoribus iam cognitis sub-

mittendis, reperitur:

$2a = -3, 837 - 0, 038 b$ et $4ab = -1, 073 - 0, 019 a$

hincque $a = -2, 051$ et $b = -0, 277$

ex quibus porro elicimus: $a = -12, 595$ et $b = -0, 086$

et $d' = -23,510$. Deinde pro reliquis iterum

$\mathcal{G} = + 32, 663$. . . $\mathcal{H} = 1, 514059$

$\mathcal{K} = -1, 035$. . . $L\mathcal{K} = 0, 014776$

$J' = -2(a-n)J = 5, 060;$

$K' = 2(a+n)K = 0, 227;$

$J = -15, 555$. . . $LJ = 1, 191891$

$K = -0, 370$. . . $LK = 9, 568589$

Porro $\mathcal{Q} = -1, 453$. . . $L\mathcal{Q} = 0, 162070$

$\mathcal{M} = -0, 000$. . .

$L' = 2(2a-1) L = 12, 786$

$M' = 2(2a+1) M$

$L = + 6, 252$. . . $L L = 0, 796019$

$M = -0, 001$. . . $L M = 7, 000000$

Denique $\delta = -0, 123$ et $H = -1, 033$

argue $\frac{1}{2} \delta - \gamma = -7, 459 k k$

§. 97. His igitur valoribus inventis innotescet primum distantia Lunae a terra curvata, quaerens a foia
L 2 excen-

excentricitate orbis lunaris k pendet. Cum enim
 haec differentia posita sit $n = \frac{(1-k)an}{1-k \cos f}$ ob $n = 1 + \frac{v}{m}$, erit

$$\begin{aligned} n &= 1 + 0,007161 \cos 2\eta - 0,0719 \cos 4\eta \\ &+ 0,000073 \cos 6\eta - 0,0005 \cos 8\eta \\ &+ 0,194888 \cos(2\eta-\eta) - 0,003274 \cos(2\eta+\eta) \\ &+ 0,003238 \cos(4\eta-\eta) + 0,000078 \cos(4\eta+\eta) \\ &+ 0,0059 \cos 2\eta \\ &+ 0,0889 \cos(2\eta-2\eta) - 0,0021 \cos(2\eta+2\eta) \\ &+ 0,0357 \cos(4\eta-2\eta) \end{aligned}$$

At pro longitudine Lunae, quatenus a sola excentricitate k pendet, probabitur $\frac{d\phi}{dr} =$

$$\begin{aligned} &+ 0,000085 + 0,019015 \cos 2\eta + 0,000076 \cos 4\eta \\ &+ 0,1562 \cos 2\eta + 0,0008 \cos 4\eta \\ &+ 0,001255 \cos f - 0,38410 \cos(2\eta-\eta) + 0,002647 \cos(4\eta-\eta) \\ &+ 0,01278 \cos(2\eta+\eta) - 0,000229 \cos(4\eta+\eta) \\ &+ 0,0118 \cos 2\eta - 0,0081 \cos(2\eta-2\eta) - 0,0076 \cos(4\eta-2\eta) \\ &+ 0,0102 \cos(2\eta+2\eta) \end{aligned}$$

§. 98. Ponatur nunc:

$$\begin{aligned} \phi &= O + \sin 2\eta + a' \cos 2\eta + \sin 4\eta + b' \cos 4\eta \\ &+ \sin 2\eta + \sin(2\eta-\eta) + \sin(4\eta-\eta) \\ &+ \sin 2\eta - \sin(2\eta+\eta) + \sin(4\eta+\eta) \\ &+ \sin(2\eta-2\eta) + \sin(4\eta-2\eta) \\ &+ \sin(2\eta+2\eta) + \sin(4\eta+2\eta) \end{aligned}$$

arque

arque differentiando orientur sequentes comparationes

$$\begin{aligned} n + 0,000285 &= O - \frac{a'(2nA+\mathcal{D})-\mathcal{D}'(2aD+\mathcal{D})}{n} + 0,000190 \\ &+ 0,1562 = 2a a' - \frac{\mathcal{D}'(\mathcal{D})}{n} (2n+\mathcal{D}) - 2\mathcal{D}'(2nD+\mathcal{D}) \\ &+ 0,0008 = 4a b' - \frac{a'(2nA+\mathcal{D})-\mathcal{D}'(2nD+\mathcal{D})-2(\mathcal{D}'+\mathcal{D})(2n+\mathcal{D})}{n} \\ &+ 0,0118 = 2\mathcal{D}' - \frac{\mathcal{D}'(2nD+\mathcal{D})-\mathcal{D}'(2nH+\mathcal{D})-\mathcal{D}'(\mathcal{D})-\mathcal{D}'(2nA+\mathcal{D})}{n} \\ &- 0,0081 = 2(a-1)\mathcal{D}' - \frac{3\mathcal{D}'}{2n} - \frac{\mathcal{D}'(2n\mathcal{D})-\mathcal{D}'(2nH+\mathcal{D})}{n} \\ &+ 0,0102 = 2(a+1)\mathcal{D}' - \frac{3\mathcal{D}'}{2n} - \frac{\mathcal{D}'(2nH+\mathcal{D})-2\mathcal{D}'(2nD+\mathcal{D})}{n} \\ &- 0,0076 = 2(2a-1)\mathcal{D}' - \frac{3\mathcal{D}'}{2n} - \frac{\mathcal{D}'(2nH+\mathcal{D})-\mathcal{D}'(2nA+\mathcal{D})}{n} \\ &+ \frac{\mathcal{D}'(2nD+\mathcal{D})}{n} - \frac{2\mathcal{D}'(2n+\mathcal{D})}{n} \\ &+ \frac{3\mathcal{D}'}{n} - \frac{2\mathcal{D}'(2n+\mathcal{D})}{n} \end{aligned}$$

§. 99. Ex his comparationibus elicimus:

$$\begin{aligned} a' &= + 0,0509; & b' &= 0,0008 \\ \mathcal{D}' &= + 0,5385; & \mathcal{D}' &= 0,0028 \\ \mathcal{D} &= - 0,1055; & \mathcal{D} &= 0,0000 \\ \mathcal{D}' &= + 0,0021; & \text{et } O &= n-0,000429 \end{aligned}$$

L 3

posito

posito $k = 0,05445$. Hinc autem erit $\frac{1}{2}\delta - \gamma = -0,02302$
 Cum autem iam ante inuentum esset $\frac{1}{2}\delta - \gamma = -0,01742$
 erit reuera $\frac{1}{2}\delta - \gamma = -0,00560$. Tum vero inuenimus:
 $\gamma = 1,40673$, vnde erit $\frac{1}{2}\delta = 1,40113$, et $\delta = 2,80226$
 hincque $2\gamma - \frac{1}{2}\delta = -1,38993$ et $\frac{2\gamma - \frac{1}{2}\delta}{mz} = -0,00794$.
 Verum ex cognita ratione motus medii ad motum anno-
 maliae est $0 = 1,0085272$, vnde $x = 1,0089562$
 Verum esse debet $x = 1 + \frac{3 + 4\mu - \delta}{4mz}$; vnde foret
 $0,0089562 = 0,008289 + \frac{\mu}{mz}$; ideoque $\frac{\mu}{mz} = 0,000667$
 qui valor cum sit tam exiguus, merito dubitamus,
 num μ non proflus sit $= 0$.

CAPUT

C

0,02302
 0,01742
 inuenimus:
 2,80226

3,00794.

C

in ano-
 3089562

foret

000667

P

nitamus,

R

CAPUT VII.

CORRECTIO INAEQUALITATUM LUNAE, ANTE INVENTARUM.

§. 100.

Q uoniam nunc quidem valores litterarum γ et δ
 ita inuenimus, vt eos pro proxime veris habere
 queamus, ex his coefficientes terminorum, quibus
 inaequalitates lunae continentur, accuratius definire po-
 terimus. Cum enim sit $\gamma = 1,40673$ et $\delta = 2,80226$,
 colligamus hic in vnum omnes formulas, quas hactenus
 pro inueniendis coefficientibus assumis eliciuimus. Po-
 fueramus autem:

$$\begin{aligned}
 \sqrt{Rd} &= \mathcal{Q} k \cos 2\gamma + a k k \cos 2\gamma + \mathcal{R} \cos 4\gamma + b k k \cos 4\gamma \\
 &+ \mathcal{S} k \cos \gamma + \mathcal{D} k \cos (2\gamma - \gamma) + \mathcal{F} k \cos (4\gamma - \gamma) \\
 &+ \mathcal{G} k \cos (2\gamma + \gamma) + \mathcal{H} k \cos (4\gamma + \gamma) \\
 &+ \mathcal{I} k k \cos 2\gamma + \mathcal{J} k^2 \cos (2\gamma - 2\gamma) + \mathcal{K} k^2 \cos (4\gamma - 2\gamma) \\
 &+ \mathcal{L} k^2 \cos (2\gamma + 2\gamma) + \mathcal{M} k^2 \cos (4\gamma + 2\gamma) \\
 &= A \cos 2\gamma + a k k \cos 2\gamma + B \cos 4\gamma + b k k \cos 4\gamma \\
 &+ D k \cos (2\gamma - \gamma) + F k \cos (4\gamma - \gamma) \\
 &+ E k \cos (2\gamma + \gamma) + G k \cos (4\gamma + \gamma) \\
 &+ H k k \cos 2\gamma + J k k \cos (2\gamma - 2\gamma) + L k k \cos (4\gamma - 2\gamma) \\
 &+ K k k \cos (2\gamma + 2\gamma) + M k k \cos (4\gamma + 2\gamma)
 \end{aligned}$$

CAPUT

§. 101.